CE-ATA Digital Protocol

Revision 1.0
2-March-2005

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This 1.0 revision of the CE-ATA Digital Protocol specification ("Final Specification") is available for download at www.ce-ata.org.

For more information about CE-ATA, refer to the CE-ATA Workgroup website at www.ce-ata.org.

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1. Introduction

1.1. Goals, Objectives, & Constraints

This specification defines a physical and logical interface between a storage device and a host.

Some of the goals and requirements for the specification include:

- Optimized for handheld embedded applications of storage
- Low/minimal pin count
- Accommodates fast time-to-market initial solution leveraging existing technologies
- Provides interface transfer rates sufficient for current small form factor disk drives with performance scalability to support several future product generations
- Consistent with ATA software infrastructure, but complete legacy software compatibility is not a requirement
- Only a single device need be accommodated per connection

CE-ATA is supported over the MMC electrical interface using a protocol that utilizes the existing MMC access primitives. The interface electrical and signaling definition is as defined in the MMC reference.

1.2. References

This specification makes reference to the following specifications:

MMC System Specification v 4.0 available to MMCA members under NDA. The CE-ATA specification builds on the MMC specification. Refer to MMCA for IP terms for MMC material.

MMC Systems Summary Specification v 3.31 available at http://www.mmca.org/tech/MMC-System-Summary-v3.31.pdf

AT Attachment with Packet Interface – 6 (ATA/ATAPI-6) [INCITS 361:2002]. Published ATA/ATAPI specifications available from ANSI at webstore.ansi.org or from Global Engineering.

1.3. Definitions, abbreviations, and conventions

1.3.1. Definitions and Abbreviations

The terminology used in this specification is intended to be self-sufficient and does not rely on overloaded meanings defined in other specifications. Terms with specific meaning not directly clear from the context are clarified in the following sections.

1.3.1.1. ATA (AT Attachment)

ATA defines the physical, electrical, transport, and command protocols for the internal attachment of storage devices as defined in the ATA reference.

1.3.1.2. BSY

BSY corresponds to bit 7 in the ATA Status register. BSY is set to one to indicate that the device is busy. The ATA BSY signal has no relationship to the MMC Busy signal. Refer to the ATA reference for more information on the BSY bit.

1.3.1.3. CE

CE is the acronym used for “Consumer Electronics” and commonly refers to consumer and handheld electronic devices.

1.3.1.4. CE-ATA sector size

CE-ATA sector size corresponds to the value reported in IDENTIFY DEVICE word 106, refer to Section 4.2.1.4.

1.3.1.5. Data unit

The term “data unit” describes 512 bytes of data. All CE-ATA data transfers are an integral multiple of data units.

1.3.1.6. DATx

DATx refers to an MMC data line, where ‘x’ signifies a particular data line (0 through 7). An MMC design may support one, four, or eight data lines. See the MMC reference.

1.3.1.7. Dword

A Dword is thirty-two (32) bits of data. A Dword may be represented as 32 bits, as two adjacent words, or as four adjacent bytes. When shown as bits the least significant bit is bit 0 and most significant bit is bit 31. The most significant bit is shown on the left. When shown as words the least significant word (lower) is word 0 and the most significant (upper) word is word 1. When shown as bytes the least significant byte is byte 0 and the most significant byte is byte 3. A Dword alignment/granularity means that address/count bits 1-0 are zero.

1.3.1.8. E

‘E’ is used to indicate the end bit of an MMC command. For more details, see Section 3.

1.3.1.9. L

‘L’ is used to indicate a one cycle pull-down on the MMC interface. For more details, see Section 3.

1.3.1.10. MMC data block

An MMC data block corresponds to a data transfer on the MMC data lines that includes a start bit, the data to transfer, a 16-bit CRC and the end bit. The size of the MMC data block does not include the start bit, CRC, or the end bit. Refer to Section 2.3 for the allowed MMC data block sizes that may be used with RW_MULTIPLE_BLOCK (CMD61).

1.3.1.11. MMC Busy

MMC Busy corresponds to the device asserting MMC data line DAT0 to indicate to the host that the device is not yet ready to receive data on the MMC bus. The MMC Busy signal has no relationship to the ATA BSY signal. Refer to the MMC reference for more information.

1.3.1.12. P

‘P’ is used to indicate a one cycle pull-up on the MMC interface. For more details, see Section 3.

1.3.1.13. S

‘S’ is used to indicate the start bit of an MMC command. For more details, see Section 3.

1.3.1.14. word

A word is sixteen (16) bits of data. A word may be represented as 16 bits or as two adjacent bytes. When shown as bits the least significant bit is bit 0 and most significant bit is bit 15. The most significant bit is shown on the left. When shown as bytes the least significant byte (lower) byte is byte 0 and the most significant byte (upper) byte is byte 1. The definition of a word in CE-ATA is the same as the definition of a word in ATA. A word alignment/granularity means that address/count bit 0 is zero.

1.3.1.15. Z

'Z' is used to indicate a one cycle high impedance state on the MMC interface. For more details, see Section 3.

1.3.2. Conventions

The names of abbreviations, ATA commands, fields, and acronyms used as signal names are in all uppercase (e.g., IDENTIFY DEVICE). MMC commands are in uppercase with underscores between words (e.g., RW_MULTIPLE_BLOCK). Fields containing only one bit are usually referred to as the "name" bit instead of the "name" field.

Names of device registers begin with a capital letter (e.g., LBA Low register).

1.3.2.1. Precedence

If there is a conflict between text, figures, state machines, and tables, the precedence shall be state machines, tables, figures, and then text.

1.3.2.2. Keywords

Several keywords are used to differentiate between different levels of requirements.

1.3.2.2.1. mandatory

A keyword indicating items to be implemented as defined by this specification.

1.3.2.2.2. may

A keyword that indicates flexibility of choice with no implied preference.

1.3.2.2.3. optional

A keyword that describes features that are not required by this specification. However, if any optional feature defined by the specification is implemented, the feature shall be implemented in the way defined by the specification.

1.3.2.2.4. reserved

A keyword indicating reserved bits, bytes, words, fields, and code values that are set-aside for future standardization. Their use and interpretation may be specified by future extensions to this or other specifications. A reserved bit, byte, word, or field shall be cleared to zero, or in accordance with a future extension to this specification. The recipient shall not check reserved bits, bytes, words, or fields.

1.3.2.2.5. shall

A keyword indicating a mandatory requirement. Designers are required to implement all such mandatory requirements to ensure interoperability with other products that conform to the specification.

1.3.2.2.6. should

A keyword indicating flexibility of choice with a strongly preferred alternative. Equivalent to the phrase "it is recommended".

1.3.3. Value representations

Values that are not immediately followed by a lowercase "b" or "h" are decimal values. Values that are immediately followed by a lowercase "b" (e.g., 01b) are binary values. Values that are immediately followed by a lowercase "h" (e.g., 3Ah) are hexadecimal values.

2. Command Protocol

2.1. Access Primitives & Protocol

The following sections define the protocol for the access and command primitives.

CE-ATA makes use of the following MMC commands:

CMD0	-	GO_IDLE_STATE
CMD12	-	STOP_TRANSMISSION
CMD39	-	FAST_IO
CMD60	-	RW_MULTIPLE_REGISTER
CMD61	-	RW_MULTIPLE_BLOCK

The device shall support the MMC commands required to achieve the MMC TRAN state during device initialization. Other interface configuration settings, such as bus width, may require additional MMC commands also be supported. See the MMC reference.

GO_IDLE_STATE (CMD0), STOP_TRANSMISSION (CMD12), and FAST_IO (CMD39) are as defined in the MMC reference.

RW_MULTIPLE_REGISTER (CMD60) and RW_MULTIPLE_BLOCK (CMD61) are MMC commands defined by CE-ATA.

Note that in the figures showing the definitions of MMC commands, the MMC convention is to transmit bit 7 of byte 5 first on the interface.

2.1.1. RW_MULTIPLE_REGISTER (CMD60)

The RW_MULTIPLE_REGISTER (CMD60) command allows the reading and writing of one or more registers with a single MMC command. Register accesses with this MMC command are always for an integral number of Dwords and have a Dword aligned register address. The RW_MULTIPLE_REGISTER (CMD60) command supports issuing an ATA command by having the complete ATA task file image transmitted in a single MMC command sequence. Figure 1 depicts the RW_MULTIPLE_REGISTER (CMD60) command structure.

The host shall not issue a RW_MULTIPLE_REGISTER (CMD60) to an address range outside the task file when there is an ATA command outstanding.

The device response to RW_MULTIPLE_REGISTER (CMD60) when parameter WR=0 (R) is R1 as defined in the MMC reference. The device may transmit an MMC data block to the host as defined in Section 2.4.

The device response to RW_MULTIPLE_REGISTER (CMD60) when parameter WR=1 (W) is R1b as defined in the MMC reference indicating an optional MMC Busy status to the host. When MMC Busy status is de-asserted, the host may transmit an MMC data block to the device as defined in Section 2.4.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_REGISTER (60)					
			1	1	1	1	0	0
4	WR	Reserved (0)						
3	Address [7:2]						0	0
2	Reserved (0)							
1	Byte Count [7:2]						0	0
0	CRC							1

Figure 1 Command format for RW_MULTIPLE_REGISTER (CMD60)

Address — The starting register address for the read/write. The address shall be Dword aligned (i.e. the two least significant bits shall be zero).

Byte Count — The number of bytes to read or write. The byte count shall be an integral number of Dwords (i.e. the two least significant bits shall be zero).

WR — Flag indicating whether the operation is a read from the registers or a write to the registers. If cleared to zero indicates a read operation. If set to one indicates a write operation.

Reserved — Reserved values shall be cleared to zero by the host. Devices shall not be sensitive to the value of reserved fields.

2.1.2. RW_MULTIPLE_BLOCK (CMD61)

The RW_MULTIPLE_BLOCK (CMD61) command is the mechanism by which the ATA data payload is transferred. Figure 2 depicts the RW_MULTIPLE_BLOCK (CMD61) command structure.

The size of the MMC data block(s) transferred as part of satisfying the RW_MULTIPLE_BLOCK (CMD61) command shall not be greater than 4KB in size to ensure robust CRC strength. The MMC data block transfer size shall be 512 bytes, 1KB, or 4KB, as negotiated by the host; no other MMC data block transfer size shall be transmitted by host or device. The start bit, CRC16, and end bit that are transmitted on each data line are not included in the transfer size. Each RW_MULTIPLE_BLOCK (CMD61) request may consist of multiple MMC data block transfers in order to satisfy the requested Data Unit Count.

When interrupts are enabled for the ATA command (nIEN=0 in the ATA Control register), the Data Unit Count specified shall correspond to the entire transfer size for the ATA command. When interrupts are enabled, only one RW_MULTIPLE_BLOCK (CMD61) command may be used to complete the ATA command in order to avoid any collision condition with the command completion signal.

When interrupts are disabled for the ATA command (nIEN=1 in the ATA Control register), multiple RW_MULTIPLE_BLOCK (CMD61) commands may be used to complete the entire transfer size for the ATA command. Each individual RW_MULTIPLE_BLOCK (CMD61) shall have a Data Unit Count that corresponds to a multiple of the CE-ATA sector size for media access commands. Restricting the Data Unit Count in this manner avoids splitting CE-ATA sectors across RW_MULTIPLE_BLOCK (CMD61) commands.

The device response to RW_MULTIPLE_BLOCK (CMD61) when parameter WR=0 (R) is R1 as defined in the MMC reference. The device response to RW_MULTIPLE_BLOCK (CMD61) when parameter WR=1 (W) is R1b as defined in the MMC reference indicating an optional MMC Busy status to the host.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_BLOCK (61)					
			1	1	1	1	0	1
4	WR	Reserved (0)						
3	Reserved (0)							
2	Data Unit Count [15:8]							
1	Data Unit Count [7:0]							
0	CRC							1

Figure 2 Command format for RW_MULTIPLE_BLOCK (CMD61)

Data Unit Count The number of 512 byte units of data to be transferred between the host and device. For media access ATA commands, e.g. READ DMA EXT, the Data Unit Count shall be a multiple of the CE-ATA sector size supported by the device. For example, if the device has a 4KB CE-ATA sector size then the three least significant bits of Data Unit Count shall be zero. Data Unit Count does not necessarily correspond to the number of MMC data blocks required to complete the RW_MULTIPLE_BLOCK (CMD61) command. For example, if the MMC data block size is 1KB and the Data Unit Count is 16 then there will be eight MMC data block transfers to complete the RW_MULTIPLE_BLOCK (CMD61) command. A value of 0h indicates that no data is to be transferred; this is used for triggering interrupts for ATA non-data commands (see Section 3.2.5).

WR Flag indicating whether the operation is a read from the device or a write to the device. If cleared to zero indicates a read operation (data transfer is from device to host). If set to one indicates a write operation (data transfer is from host to device).

Reserved Reserved values shall be cleared to zero by the host. Devices shall not be sensitive to the value of reserved fields.

2.2. Command Completion Signal

CE-ATA defines a command completion signal that the device uses to notify the host upon normal ATA command completion or when ATA command termination has occurred.

The command completion signal is only sent when the ATA command is complete, at this time the device shall no longer transfer any data on the DATx lines. The device may only transmit one command completion signal per ATA command.

The device shall only transmit a command completion signal to the host after a RW_MULTIPLE_BLOCK (CMD61) has been issued by the host and the device has returned the R1(b) response for that MMC command and interrupts are enabled (nIEN=0 in the ATA Control register) .

The device issues a command completion signal by sending a single zero bit in push-pull mode on the CMD line. The device shall then go to the high impedance state on the CMD and DATx lines until the device receives a new MMC command from the host. Device timing requirements for the command completion signal are detailed in Section 3.

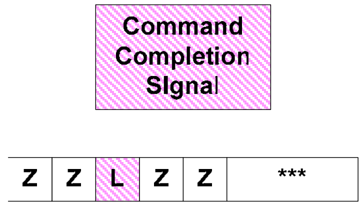


Figure 3 Device command completion signal

After the host detects a command completion signal from the device, it should issue a FAST_IO (CMD39) command to read the ATA Status register to determine the ending status for the ATA command.

2.2.1. CMD line state after command completion signal

It is recommended that host implementations pull the CMD line high two clocks after the device transmits the command completion signal to ensure that the CMD line is not left floating. The command completion signal is the only MMC command, MMC response, or signal that leaves the CMD line in a floating condition.

If the host does not explicitly pull the CMD line high it will drift back to the high impedance state due to the pull-up resistor on the CMD line. During the time that the CMD line is left floating, the device may falsely detect noise events as the start of a new packet. The structure of MMC commands (a start bit, followed by a transmit bit, followed by a valid command index, ending with a CRC and end bit) will ensure that any accidental packet detection due to noise will not be acted on by the device. Conservative designs may also require that a valid MMC command be preceded with eight consecutives one bits on the CMD line for additional noise suppression. The minimum time between consecutive MMC commands is eight cycles, thus this noise suppression technique may be employed in general.

If the host does not explicitly pull the CMD line high after the command completion signal, the FAST_IO (CMD39) command to read the ATA Status register may fail if the CMD line has not yet floated back to the high impedance state such that the device cannot accurately detect the start bit of the FAST_IO (CMD39) command. In this case, the host will not receive a response for the FAST_IO (CMD39) command within the R4 response timeout period (the timeout is N_{CR} cycles, see the MMC reference). If this occurs the host should issue another FAST_IO (CMD39) command to receive the ATA ending status.

2.2.2. Command Completion Signal Disable

The host may cancel the ability for the device to return a command completion signal by issuing the command completion signal disable. The host shall only issue the command completion signal disable when it has received an R1(b) response for an outstanding RW_MULTIPLE_BLOCK (CMD61) command and interrupts are enabled (nIEN=0 in the ATA Control register).

The host issues a command completion signal disable by sending 00001b in push-pull mode on the CMD line (where zero is transmitted first). The host may precede the command completion signal disable with any number of zero bits and may append any number of one bits to the end of the command completion signal disable. The host shall issue a STOP_TRANSMISSION (CMD12) command following transmission of the command completion signal disable to abort the ATA command.

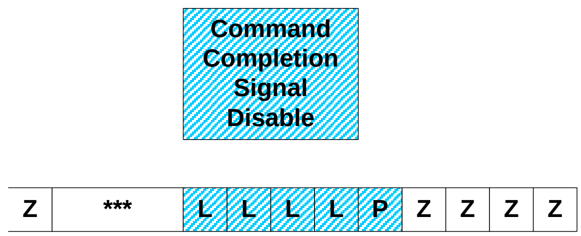


Figure 4 Host command completion signal disable

If the host begins transmission of the command completion signal disable at clock “n”, the device is required to recognize the command completion signal disable within four clock cycles of the first bit of the command completion signal disable. This is illustrated in Figure 5; note that the device must be in the high impedance state on the CMD line by clock n+4.

Clock Cycle	Host transmission on CMD line	Device may transmit on CMD line
n	‘0’	‘Z’ or ‘0’
n+1	‘0’	‘Z’ or ‘0’
n+2	‘0’	‘Z’ or ‘0’
n+3	‘0’	‘Z’ or ‘0’
n+4	‘0’ or ‘1’	‘Z’

Figure 5 Allowed Device Transmit Tokens During Command Completion Signal Disable

After reception of a command completion signal disable, the device shall not transfer a command completion signal for the current ATA command.

2.3. MMC Data Block Size Negotiation

The host and device shall negotiate the size of the MMC data block size that will be used in the RW_MULTIPLE_BLOCK (CMD61) command. By default, the MMC data block size shall be 512 bytes, as indicated by bits 1:0 being set to 00b in the scrControl register. When bits 1:0 are set to 00b in the scrControl register, the host and the device are required to have all MMC data blocks be 512 bytes in size. The host may negotiate use of a 1KB or 4KB MMC data block size.

If the device supports a 1KB MMC data block size as indicated by bit 1 being set to one in the scrCapabilities register, the host is allowed to set bits 1:0 to 01b in the scrControl register to begin using a 1KB MMC data block size. When bits 1:0 are set to 01b in the scrControl register, the host and the device are required to have all MMC data blocks be 1KB in size.

If the device supports a 4KB MMC data block size as indicated by bit 2 being set to one in the scrCapabilities register, the host is allowed to set bits 1:0 to 10b in the scrControl register to begin using a 4KB MMC data block size. When bits 1:0 are set to 10b in the scrControl register, the host and the device are required to have all MMC data blocks be 4KB in size.

Refer to Section 5.2 for the definitions of the scrCapabilities and scrControl registers.

2.4. Reduced ATA Command Emulation

The Reduced ATA Command set provides a streamlined set of disk commands similar to a subset of the ATA command set. The CE-optimized interface provides a single data transfer mode, so the various transfer mode controls defined in the ATA reference do not apply.

The RW_MULTIPLE_REGISTER (CMD60) command is used to write an ATA command packet to a set of registers (often referred to as the task file) at a specific address within the device's register space. Similarly, ATA command status is retrieved by utilizing the RW_MULTIPLE_REGISTER (CMD60) or FAST_IO (CMD39) commands to read a set of registers at a specific address within the device's register space. The form and definition of the RW_MULTIPLE_REGISTER (CMD60) command is defined in Section 2.1.1. Figure 6 depicts the mapping of the ATA registers to the MMC register space. The ATA Data register is not mapped because the ATA PIO data transfer protocol is not supported. The Alternate Status register is not mapped because interrupts are not cleared by a Status register read.

Register Address	**ATA Register (8-bit)**
0	Reserved
1	Features (exp)
2	Sector Count (exp)
3	LBA Low (exp)
4	LBA Mid (exp)
5	LBA High (exp)
6	Control
7	Reserved
8	Reserved
9	Features (write) / Error (read)
10	Sector Count
11	LBA Low
12	LBA Mid
13	LBA High
14	Device/Head
15	Command (write) / Status (read)

Figure 6   ATA task file register mapping in MMC register space

Any underlying MMC transport layer error that is known to the device will cause an outstanding ATA command to be aborted; the host should retry the entire ATA command. The ATA Status register will have the ERR bit set to one and an appropriate error code will be set in the ATA Error register. If an MMC transport layer error occurs when an ATA command has not yet been successfully issued to the device, the MMC error will not be recorded in the ATA Status or Error registers.

On read operations, the device is not aware of any CRC errors that may occur during the data transfer. The host is responsible for checking the host's MMC status register to determine if any MMC layer error has occurred. If an MMC layer error has occurred during execution of an ATA command, the host shall complete the ATA command with error status.

A read of the ATA Control register shall return the last value written. The high-order bit (HOB) defined in the ATA reference in the ATA Control register is reserved in CE-ATA. The host shall not set the HOB bit to one; if HOB is set to one then the device behavior is indeterminate.

When interrupts are disabled (nIEN=1 in the ATA Control register), the host should poll prior to each RW_MULTIPLE_BLOCK (CMD61) issued to determine whether an error condition has occurred. It is recommended that the host poll until the BSY bit is de-asserted in the ATA Status register. If BSY=0 and DRQ=1 in the ATA Status register then the host should issue the RW_MULTIPLE_BLOCK (CMD61) command. If BSY=0 and ERR=1 then the ATA command has completed with error and the host should use FAST_IO (CMD39) to determine the cause of the error.

2.4.1. Reset and Device Discovery

The underlying MMC reset and initialization procedure for establishing communications between the host and the device is not reproduced here and is as defined in the MMC reference.

Reception of the GO_IDLE_STATE (CMD0) command shall reset the MMC layer as defined in the MMC reference and shall perform a hard reset to the ATA layer as defined in the ATA reference. When this MMC command is received, there is no requirement for the device to maintain data coherency. After a GO_IDLE_STATE (CMD0), the MMC TRAN state will need to be negotiated to and MMC layer settings will need to be re-initialized.

An ATA software reset is performed by issuing two FAST_IO (CMD39) commands back-to-back to the ATA Control register. The first FAST_IO (CMD39) command shall have the SRST bit set to one. The second FAST_IO (CMD39) command shall have the SRST bit cleared to zero. The host shall not set the SRST bit in the ATA Control register to one using RW_MULTIPLE_REGISTER (CMD60). An ATA software reset shall have no effect on the MMC layer. There is no timing requirement between the setting and clearing of the SRST bit in the ATA Control register.

The host determines the presence of a CE-ATA device by issuing FAST_IO (CMD39) commands or the RW_MULTIPLE_REGISTER (CMD60) command as defined in Section 2.1.1 after the interface has entered the MMC TRAN state in order to read the present contents of the task file registers. In the presence of a CE-ATA device, the FAST_IO (CMD39) and RW_MULTIPLE_REGISTER (CMD60) commands will succeed and the returned data will be the CE-ATA reset signature as defined in Figure 7.

Upon power-on reset, reception of the MMC command GO_IDLE_STATE (CMD0), or ATA software reset, CE-ATA devices shall initialize the task file registers to the values indicated in Figure 7. Note that upon reset or power-on, CE-ATA devices shall set the nIEN bin in the Control register to one.

Register Address	ATA Register (8-bit)	Reset Value (read)							
0	Reserved	Reserved							
1	Features (exp)	Reserved							
2	Sector Count (exp)	Reserved							
3	LBA Low (exp)	Reserved							
4	LBA Mid (exp)	Reserved							
5	LBA High (exp)	Reserved							
6	Control	Reserved					0 SRST	1 nIEN	0
7	Reserved	Reserved							
8	Reserved	Reserved							
9	Error	Reserved							
10	Sector Count	Reserved							
11	LBA Low	Reserved							
12	LBA Mid	CEh							
13	LBA High	AAh							
14	Device/Head	Reserved							NBR
15	Status	0 BSY	1 DRDY	R cs	R cs	0 DRQ	R cs	R cs	0 ERR

Figure 7 Device reset signature (initial task file contents)

NBR If set to one, the device does not automatically reallocate degraded blocks. If cleared to zero, the device automatically reallocates degraded blocks.

cs fields have command specific meanings

Devices shall not spin up rotating media by default upon power-up. Refer to the definition of the STANDBY IMMEDIATE command in Section 4.2.4 for the conditions under which the device shall spin up the media.

2.4.2. Device MMC State Machine

The MMC state machine describes the required MMC behavior for CE-ATA devices. The MMC layer is decomposed into a command state machine and a data state machine. The command state machine is responsible for the CMD line on the MMC bus and is in control of the MMC layer. The data state machine is responsible for the DATx lines on the MMC bus. The data state machine performs operations as requested by the command state machine and primarily acts as a data movement engine.

2.4.2.1. Device MMC Command State Machine

DC1: DC_Reset[1,2]	Notify ATA layer that GO_IDLE_STATE (CMD0) has been received.		
	1. Unconditional	→	DC_WaitForATAReset
	NOTE: 1. This state is entered asynchronously as a result of GO_IDLE_STATE (CMD0) being received and on power-up. 2. The device shall not complete negotiation to the MMC TRAN state in this state.		

DC2: DC_WaitForATAReset[1]	Wait for ATA layer to complete reset.		
	1. ATA layer has notified MMC layer that reset is complete	→	DC_MMCTran
	2. ATA layer has not notified MMC layer that reset is complete	→	DC_WaitForATAReset
	NOTE: 1. The device shall not complete negotiation to the MMC TRAN state in this state.		

DC3: DC_MMCTran	Complete negotiation to the MMC TRAN state.		
	1. Device has negotiated to MMC TRAN state	→	DC_Idle
	2. Device has not negotiated to MMC TRAN state	→	DC_MMCTran

DC4: DC_Idle	Wait for MMC command from host.		
	1. MMC command received	→	DC_CmdChkCrc
	2. MMC command not received	→	DC_Idle

DC5: DC_CmdChkCrc	Calculate CRC based on MMC command received and compare to received CRC.		
	1. Calculated CRC and received CRC are equal	→	DC_CmdChkType
	2. Calculated CRC and received CRC are different	→	DC_Idle[1]
	NOTE: 1. ATA layer is notified that an MMC layer error occurred.		

DC6: DC_CmdChkType	Determine if the command received is a valid MMC command.		
	1. RW_MULTIPLE_REGISTER (CMD60) received or RW_MULTIPLE_BLOCK (CMD61) received		DC_Cmd6X_Entry
	2. FAST_IO (CMD39) received		DC_Cmd39_Entry
	3. STOP_TRANSMISSION (CMD12) received		DC_Cmd12_Entry
	4. Command index not equal to 12, 39, 60, or 61	→	DC_Idle[1]
	NOTE: 1. ATA layer is notified that an illegal MMC command was received.		

DC7: DC_IntWait	Wait for ATA layer request to send command completion signal or the host to send command completion signal disable.		
	1. Start bit detected from host on CMD line	→	DC_Idle
	2. ATA layer has requested transmission of command completion signal[1] and no start bit detected from host on CMD line	→	DC_Interrupt
	3. ATA layer has not requested transmission of command completion signal and no start bit detected from host on CMD line	→	DC_IntWait
	NOTE: 1. The ATA layer may have requested transmission of the command completion signal prior to entry into this state. The MMC layer shall latch this request until a new RW_MULTIPLE_REGISTER (CMD60) command is received.		

DC8: DC_Interrupt	Transmit a single ‘0’ on the CMD line (the command completion signal).		
	1. Unconditional	→	DC_Idle

2.4.2.1.1. Device CMD6X States

DC9: DC_Cmd6X_Entry	Device pulls up the CMD line. If WR=1 (W), notify MMC Data layer that MMC Busy may be asserted. If MMC command received was RW_MULTIPLE_REGISTER (CMD60) clear any pending request for a command completion signal to be sent.		
	1. R1 response is ready for transmission	→	DC_Cmd6X_R1
	2. R1 response is not ready for transmission	→	DC_Cmd6X_Entry

DC10: DC_Cmd6X_R1	Transmit R1 response with Card Status set to 0h.		
	1. R1 response transmission complete	→	DC_Cmd6X_Data
	2. R1 response transmission not complete	→	DC_Cmd6X_R1

DC11: DC_Cmd6X_Data	Notify MMC Data layer that data may be transferred.		
	1. MMC command received was RW_MULTIPLE_BLOCK (CMD61) and ATA layer has notified MMC layer that interrupts are enabled	→	DC_IntWait
	2. MMC command received was not RW_MULTIPLE_BLOCK (CMD61) or ATA layer has notified MMC layer that interrupts are disabled	→	DC_Idle

2.4.2.1.2. Device CMD39 States

The host shall not issue a FAST_IO (CMD39) to an address range outside the task file when there is an ATA command outstanding.

DC12: DC_Cmd39_Entry	Device pulls up the CMD line.		
	1. Register Write field cleared to zero (read)	→	DC_Cmd39_ReadReg
	2. Register Write field set to one (write)	→	DC_Cmd39_WriteReg

DC13: DC_Cmd39_ReadReg	Read the contents of the Register Address specified in FAST_IO (CMD39) and prepare it for transmission to the host.		
	1. Register contents ready for transmission	→	DC_Cmd39_R4
	2. Register contents not ready for transmission	→	DC_Cmd39_ReadReg

DC14: DC_Cmd39_WriteReg	Write the Register Data specified to the Register Address specified in FAST_IO (CMD39).		
	1. Register contents have been written	→	DC_Cmd39_R4
	2. Register contents have not been written	→	DC_Cmd39_WriteReg

DC15: DC_Cmd39_R4	Transmit R4 response with Register Data filled in based on current contents of Register Address. If WR=1 (W), notify ATA layer of register write.		
	1. R4 response transmission complete	→	DC_Idle
	2. R4 response transmission not complete	→	DC_Cmd39_R4

2.4.2.1.3. Device CMD12 States

DC16: DC_Cmd12_Entry	Device pulls up the CMD line. Notify ATA layer of ATA command abort. Notify MMC Data layer to stop any data transmission.		
	1. R1 response is ready for transmission.	→	DC_Cmd12_R1
	2. R1 response is not ready for transmission.	→	DC_Cmd12_Entry

DC17: DC_Cmd12_R1	Transmit R1 response with Card Status set to 0h.		
	1. R1 response transmission complete	→	DC_Idle
	2. R1 response transmission not complete	→	DC_Cmd12_R1

2.4.2.2. MMC Data State Machine

DD1: DD_Idle	Wait for MMC Command layer instruction.		
	1. MMC Command layer has indicated MMC Busy may be asserted and ATA layer is not ready to receive data	→	DD_AssertBsy
	2. MMC Command layer has indicated data may be transferred	→	DD_XferType
	3. MMC Command layer has not provided any instruction or ATA layer is ready to receive data	→	DD_Idle

DD2: DD_AssertBsy	Assert MMC Busy on DAT0.		
	1. ATA layer is ready to receive data	→	DD_Idle
	2. ATA layer is not ready to receive data	→	DD_AssertBsy

DD3: DD_XferType	Decode MMC transfer type.		
	1. MMC command was RW_MULTIPLE_REGISTER (CMD60) with WR=0 (R)	→	DD_Cmd60R_Entry
	2. MMC command was RW_MULTIPLE_REGISTER (CMD60) with WR=1 (W)	→	DD_Cmd60W_Entry
	3. MMC command was RW_MULTIPLE_BLOCK (CMD61) with WR=0 (R)	→	DD_Cmd61R_Entry
	4. MMC command was RW_MULTIPLE_BLOCK (CMD61) with WR=1 (W)	→	DD_Cmd61W_Entry

2.4.2.2.1. Device CMD60 Read Data States

DD4: DD_Cmd60R_Entry	Transmit requested register contents and CRC to the host		
	1. MMC Command layer requested data transfer stop	→	DD_Idle
	2. Transfer of register contents and CRC complete and MMC Command layer has not requested data transfer stop	→	DD_Idle[1]
	3. Transfer of register contents and CRC not complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd60R_Entry
	NOTE: 1. The host is responsible for detecting any CRC error that has occurred and completing RW_MULTIPLE_REGISTER (CMD60) with error in that case.		

2.4.2.2.2. Device CMD60 Write Data States

DD5: DD_Cmd60W_Entry	Receive register contents from host.		
	1. MMC Command layer requested data transfer stop	→	DD_Idle
	2. Reception of register contents and CRC complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd60W_ChkCrc
	3. Reception of register contents and CRC not complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd60W_Entry

DD6: DD_Cmd60W_ChkCrc	Transmit positive CRC status of 010b on DAT0 if calculated CRC and received CRC are equal for all data lines, else transmit negative CRC status of 101b on DAT0.		
	1. Calculated CRC and received CRC are equal for all data lines	→	DD_Cmd60W_RegWr
	2. Calculated CRC and received CRC are different for any data line	→	DD_Idle

DD7: DD_Cmd60W_RegWr	Write received contents to MMC register addresses specified and notify ATA layer of register range that was updated.		
	1. Contents written and ATA layer notified	→	DD_Idle
	2. Contents not written or ATA layer not notified	→	DD_Cmd60W_RegWr

2.4.2.2.3. Device CMD61 Read Data States

DD8: DD_Cmd61R_Entry	Wait for ATA layer to provide one MMC data block to transfer.	
1. MMC Command layer requested data transfer stop	→	DD_Idle
2. ATA layer has provided one MMC data block to transfer and MMC Command layer has not requested data transfer stop	→	DD_Cmd61R_Xmit
3. ATA layer has not provided one MMC data block transfer and MMC Command layer has not requested data transfer stop	→	DD_Cmd61R_Entry

DD9: DD_Cmd61R_Xmit	Transmit MMC data block and CRC to host.	
1. MMC Command layer requested data transfer stop	→	DD_Idle
2. Transmission of MMC data block and CRC complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd61R_ChkCnt[1]
3. Transmission of MMC data block and CRC not complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd61R_Xmit
NOTE: 1. The host is responsible for detecting any CRC error that has occurred and completing the ATA command with error in that case.		

DD10: DD_Cmd61R_ChkCnt	Notify ATA layer that MMC data block transfer complete.	
1. Data transmission satisfying the Data Unit Count specified in RW_MULTIPLE_BLOCK (CMD61) not finished	→	DD_Cmd61R_Entry
2. Data transmission satisfying the Data Unit Count specified in RW_MULTIPLE_BLOCK (CMD61) finished	→	DD_Idle

2.4.2.2.4. Device CMD61 Write Data States

DD11: DD_Cmd61W_Entry	Receive MMC data block and CRC from host.	
1. MMC Command layer requested data transfer stop	→	DD_Idle
2. Reception of MMC data block and CRC complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd61W_ChkCrc
3. Reception of MMC data block and CRC not complete and MMC Command layer has not requested data transfer stop	→	DD_Cmd61W_Entry

DD12: DD_Cmd61W_ChkCrc	Transmit positive CRC status of 010b on DAT0 if calculated CRC and received CRC are equal for all data lines, else transmit negative CRC status of 101b on DAT0.		
	1. Calculated CRC and received CRC are equal for all data lines	→	DD_Cmd61W_ChkCnt
	2. Calculated CRC and received CRC are different for any data line	→	DD_Idle[1]
	NOTE: 1. ATA layer is notified that RW_MULTIPLE_BLOCK (CMD61) was not completed successfully.		

DD13: DD_Cmd61W_ChkCnt	Notify ATA layer that MMC data block reception complete. Deliver MMC data block to ATA layer.		
	1. Data transmission satisfying the Data Unit Count specified in RW_MULTIPLE_BLOCK (CMD61) not finished and ATA layer not ready to receive more data	→	DD_Cmd61W_Bsy
	2. Data transmission satisfying the Data Unit Count specified in RW_MULTIPLE_BLOCK (CMD61) not finished and ATA layer is ready to receive data	→	DD_Cmd61W_Entry
	3. Data transmission satisfying the Data Unit Count specified in RW_MULTIPLE_BLOCK (CMD61) finished	→	DD_Idle

DD14: DD_Cmd61W_Bsy	Assert MMC Busy on DAT0.		
	1. ATA layer is ready to receive data	→	DD_Cmd61W_Entry
	2. ATA layer is not ready to receive data	→	DD_Cmd61W_Bsy

2.4.3. Device ATA State Machine Definition

The ATA state machine describes the required ATA layer behavior for CE-ATA devices.

Upon device power-up or reception of the MMC command GO_IDLE_STATE (CMD0), the device shall transition to state DA_Reset. For the sake of clarity, this transition has not been duplicated in all of the defined device states.

DA1: DA_Reset[2]	Reset device state, set task file register values to Reset Signature (see Section 2.4.1).		
	1. Internal reset not complete or Reset Signature not placed in task file registers	→	DA_Reset
	2. Internal reset complete and Reset Signature placed in task file registers	→	DA_Idle[1]
	NOTE: 1. The MMC layer is notified that the ATA layer has completed reset. 2. This state is entered asynchronously when the MMC layer indicates the MMC command GO_IDLE_STATE (CMD0) has been received.		

DA2: DA_Idle	Clear BSY=0, set DRDY=1, and clear DRQ=0 in the Status register.		
	1. Command register written by MMC layer	→	DA_ ATADecode
	2. Control register written by MMC layer and SRST[1] bit set to one	→	DA_SR_Cmd
	NOTE: 1. This transition is taken regardless of the state the device is in. For the sake of clarity, this transition is not replicated on all the other device ATA states. The SRST bit shall only be set to 1 by the host using the FAST_IO (CMD39) command.		

DA3: DA_ATADecode[1]	Set BSY=1, set DRDY=1, clear ERR=0, and clear DRQ=0 in the Status register.		
	1. Non-data command code and all command parameters valid	→	DA_ND_Cmd
	2. Data-In command code and all command parameters valid	→	DA_DI_Cmd
	3. Data-Out command code and all command parameters valid	→	DA_DO_Cmd
	4. Unrecognized command code or invalid command parameter	→	DA_BadCmd
	NOTE: 1. An invalid command parameter includes a command that has an LBA or Sector Count that does not conform to the CE-ATA sector size of the device. For example, if the device has a CE-ATA sector size of 8KB then the four least significant bits of LBA and Sector Count shall be zero or the command parameters are considered invalid.		

DA4: DA_BadCmd	Clear BSY=0, clear DRQ=0, set ERR=1, and set DRDY=1 in the Status register. Set ABRT=1 in the Error register.		
	1. nIEN in Control register set to one	→	DA_Idle
	2. nIEN in Control register cleared to zero	→	DA_Interrupt

DA5: DA_Interrupt	Signal MMC layer to issue command completion signal.		
	1. Unconditional	→	DA_Idle

DA6: DA_SR_Cmd	Set BSY=1, set DRDY=1, clear ERR=0, and clear DRQ=0 in the Status register. Set task file register values to Reset Signature[1] (see Section 2.4.1). Execute software reset.		
	1. Software reset complete and Reset Signature is in task file registers	→	DA_SR_Clear
	2. Software reset not complete or Reset Signature is not in task file registers	→	DA_SR_Cmd
	NOTE: 1. The nIEN bit in the Control register has a reset value of one, so an ATA software reset has the side effect of disabling interrupts. Hosts should re-enable interrupts after an ATA software reset if desired.		

DA7: DA_SR_Clear			
	1. SRST bit in Control register cleared to zero	→	DA_Idle
	2. SRST bit in Control register not cleared to zero	→	DA_SR_Clear

DA8: DA_Abort_Cmd	Abort any outstanding ATA command and clear BSY=0, clear DRQ=0, set ERR=1, and set DRDY=1 in the Status register. Set ABRT=1 in the Error register.		
	1. Unconditional	→	DA_Idle

2.4.3.1.1. Device ATA Non-Data Command Protocol

The ATA Non-Data command protocol is defined by the following state tables.

DA9: DA_ND_Cmd	Execute Non-Data ATA command.		
	1. Signal from MMC layer to abort command received	→	DA_Abort_Cmd
	2. Signal from MMC layer to abort command not received and command execution not complete	→	DA_ND_Cmd
	3. Signal from MMC layer to abort command not received and command execution complete	→	DA_ND_Done

DA10: DA_ND_Done	Set Status and Error register values as defined by the ATA command definition and command status. Clear BSY=0, set DRDY=1, and clear DRQ=0 in the Status register.		
	1. nIEN in Control register set to one	→	DA_Idle
	2. nIEN in Control register cleared to zero	→	DA_Interrupt

2.4.3.1.2. Device ATA Data-In Command Protocol

CE-ATA provides a single Data-In transfer protocol, so all ATA Data-In commands use the same data transfer protocol. There is no support for PIO transfers. Data-In ATA commands proceed with data transfer using the RW_MULTIPLE_BLOCK (CMD61) command. The ATA Data-In command protocol is defined by the following state tables.

DA11: DA_DI_Cmd	Execute Data-In ATA command.		
	1. Signal from MMC layer to abort command received	→	DA_Abort_Cmd
	2. Signal from MMC layer to abort command not received and data ready to transmit to host and no error encountered	→	DA_DI_DataXfer
	3. Signal from MMC layer to abort command not received and data not ready to transmit to host and no error encountered	→	DA_DI_Cmd
	4. Signal from MMC layer to abort command not received and error encountered	→	DA_DI_Done

DA12: DA_DI_DataXfer	Clear BSY=0 and set DRQ=1 in the Status register. Signal MMC layer to transmit MMC data block[1] and provide MMC data block to MMC layer.		
	1. Signal from MMC layer to abort command received	→	DA_Abort_Cmd
	2. Signal received from MMC layer that transmission complete and signal from MMC layer to abort command not received	→	DA_DI_ChkDuCnt
	3. Signal from MMC layer that transmission complete not received and signal from MMC layer to abort command not received	→	DA_DI_DataXfer
	NOTE: 1. The MMC layer block size and MMC layer Data Unit Count value is exposed to the ATA layer.		

DA13: DA_DI_ChkDuCnt	Check if Data Unit Count of RW_MULTIPLE_BLOCK (CMD61) is satisified.		
	1. Data transmission satisfying the Data Unit Count specified in the RW_MULTIPLE_BLOCK (CMD61) command not finished and (error not encountered or (error encountered and nIEN=1 in the Control register))	→	DA_DI_DataXfer
	2. Error encountered and nIEN=0 in the Control register	→	DA_DI_Done
	3. Data transmission satisfying the Data Unit Count specified in the RW_MULTIPLE_BLOCK (CMD61) command finished and (error not encountered or (error encountered and nIEN=1 in the Control register))	→	DA_DI_ChkDone

DA14: DA_DI_ChkDone	Set BSY=1 and clear DRQ=0 in the Status register. Set Status ERR bit and Error register based on current ATA command status.		
	1. Data transfer length specified in ATA command not satisfied	→	DA_DI_Cmd
	2. Data transfer length specified in ATA command satisfied	→	DA_DI_Done

DA15: DA_DI_Done	Set Status and Error register values as defined by the ATA command definition and command status. Clear BSY=0, set DRDY=1, and clear DRQ=0 in the Status register.		
	1. nIEN in Control register set to one	→	DA_Idle
	2. nIEN in Control register cleared to zero	→	DA_Interrupt

2.4.3.1.3. Device ATA Data-Out Command Protocol

CE-ATA provides a single Data-Out transfer protocol, so all ATA Data-Out commands use the same data transfer protocol. There is no support for PIO transfers. Data-Out ATA commands proceed with data transfer using the RW_MULTIPLE_BLOCK (CMD61) command. The ATA Data-Out command protocol is defined by the following state tables.

DA16: DA_DO_Cmd	Execute Data-Out ATA command.		
	1. Signal from MMC layer to abort command received	→	DA_Abort_Cmd
	2. Signal from MMC layer to abort command not received and ready to receive data from host and no error encountered	→	DA_DO_DataXfer
	3. Signal from MMC layer to abort command not received and not ready to receive data from host and no error encountered	→	DA_DO_Cmd
	4. Signal from MMC layer to abort command not received and error encountered	→	DA_DO_Done

DA17: DA_DO_DataXfer	Clear BSY=0 and set DRQ=1 in the Status register. Signal MMC layer that ATA layer is ready to receive an MMC data block from the host. Receive MMC data block from host.		
	1. Signal from MMC layer to abort command received	→	DA_Abort_Cmd
	2. Reception of MMC data block complete and signal from MMC layer to abort command not received	→	DA_DO_DataChkCrc
	3. Reception of MMC data block not complete from MMC layer and signal from MMC layer to abort command not received	→	DA_DO_DataXfer

DA18: DA_DO_DataChkCrc	Receive MMC CRC status information for last received data block.		
	1. MMC layer indicates received data does not have a CRC error	→	DA_DO_WriteData
	2. MMC layer indicates received data has a CRC error and nIEN=0 in the Control register	→	DA_DO_Done
	3. MMC layer indicates received data has a CRC error and nIEN=1 in the Control register	→	DA_DO_ChkDuCnt[1]
	NOTE: 1. The device shall set the ERR bit to one in the ATA Status register and shall set the ICRC bit to one in the ATA Error register.		

DA19: DA_DO_WriteData[1]	Signal MMC layer that ATA layer is not ready to receive data.		
	1. Processing of received data complete	→	DA_DO_ChkDuCnt
	2. Processing of received data not complete	→	DA_DO_WriteData
	NOTE: 1. Devices may traverse this state in zero cycles and yield no signal to the MMC layer that they are not ready to receive data if they are designed such that they can guarantee such readiness.		

DA20: DA_DO_ChkDuCnt	Check if Data Unit Count of RW_MULTIPLE_BLOCK (CMD61) is satisified.		
	1. Data reception satisfying the Data Unit Count specified in the RW_MULTIPLE_BLOCK (CMD61) command not finished and (error not encountered or (error encountered and nIEN=1 in the Control register))	→	DA_DO_DataXfer
	2. Error encountered and nIEN=0 in the Control register	→	DA_DO_Done
	3. Data reception satisfying the Data Unit Count specified in the RW_MULTIPLE_BLOCK (CMD61) command finished and (error not encountered or (error encountered and nIEN=1 in the Control register))	→	DA_DO_ChkDone

DA21: DA_DO_ChkDone	Set BSY=1 and clear DRQ=0 in the Status register. Set Status ERR bit and Error register based on current ATA command status.		
	1. Data transfer length specified in ATA command not satisfied	→	DA_DO_Cmd
	2. Data transfer length specified in ATA command satisfied	→	DA_DO_Done

DA22: DA_DO_Done	Set Status and Error register values as defined by the ATA command definition and command status. Clear BSY=0, set DRDY=1, and clear DRQ=0 in the Status register.		
	1. nIEN in Control register set to one	→	DA_Idle
	2. nIEN in Control register cleared to zero	→	DA_Interrupt

3. Timing Requirements

In this document all timing diagrams use the following abbreviations and identifiers.

S	Start bit (0)
T	Transmitter bit (Host=1 , Device=0)
P	One cycle pull-up (1)
L	One cycle pull-down (0)
E	End bit (1)
Z	High Impedance state (1)
D	Data bit
*	Repetition
X	Don't care
CRC	CRC check bits (7-bit)
CRC16	CRC check bits (15-bit)
	Host active
	Device active
N_{CR}	Number of cycles between the end bit of the MMC command token and the start bit of the response token. See the MMC reference.
N_{ACIO}	I/O read transmission delay. This is defined as the number of cycles between: 1. The end bit of the MMC command token and the start bit of the first data token. 2. The end bit of the previous data token and the start bit of the current data token. N_{ACIO} may vary between each data transmission block, depending on the device's internal operating condition. N_{ACIO} shall be 2 cycles minimum. The N_{ACIO} maximum value shall be no less than 10 seconds.
N_{WR}	I/O write transmission delay. This is defined as the number of cycles between: 1. The end bit of the response token and the start bit of the first data token. 2. The end bit of the previous data token and the start bit of the next data token. 3. The de-assertion of the MMC Busy signal and the start bit of the current data token. N_{WR} may vary for each data token between each data transmission block, depending on the device's internal operating condition. N_{WR} shall be 2 cycles minimum. N_{WR} has no maximum value.
N_{CCS}	Command completion signal transmission delay. This is defined as the number of cycles between: 1. The end bit of the last response token transmitted and the command completion signal. 2. The end bit of the previous data token and the command completion signal. Note: A race condition exists in the case of an error in the middle of a write to the device. A new data token may be received from the host before the command completion signal is transmitted. The command completion signal is valid if this situation occurs.

	N_{CCS} may vary for each ATA command, depending on the device's internal operating condition. N_{CCS} shall be 8 cycles minimum after a previous response token. N_{CCS} shall be 2 cycles minimum after a previous data token. N_{CCS} has no maximum value.

3.1. RW_MULTIPLE_REGISTER (CMD60) Timing Diagrams

3.1.1. Read Timings

If the host issues a RW_MULTIPLE_REGISTER (CMD60) command with WR=0 (R) to read a set of registers from the device, the following timing requirements shall be met:

- The device shall respond within N_{CR} cycles after the end bit of the RW_MULTIPLE_REGISTER (CMD60) command with an R1 response.
- Within N_{ACIO} cycles after the end bit of the RW_MULTIPLE_REGISTER (CMD60) command, the device shall start transmitting an MMC data block containing the data from the registers requested in the MMC command followed by a CRC16.

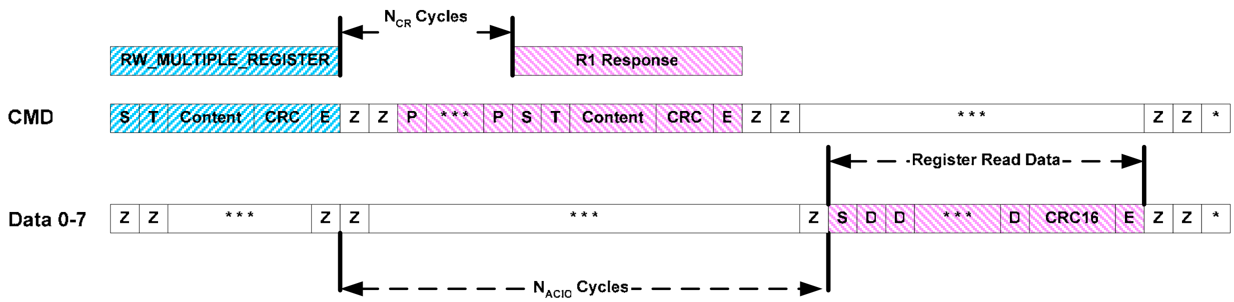


Figure 8 RW_MULTIPLE_REGISTER (CMD60) Read Timings

3.1.2. Write Timings

If the host issues a RW_MULTIPLE_REGISTER (CMD60) command with WR=1 (W) to write a set of registers in the device, the following timing requirements shall be met:

- The device shall respond within N_{CR} cycles after the end bit of the RW_MULTIPLE_REGISTER (CMD60) command with an R1b response.
- Two clocks after the end bit of the RW_MULTIPLE_REGISTER (CMD60) command, the device may optionally assert MMC Busy by pulling the DAT0 line low (L) until the device is ready to receive the data block from the host.
- Within N_{WR} cycles after the end bit of the R1b response and MMC Busy is de-asserted, the host shall start the data transmission to the device. The host shall not start data transmission to the device before MMC Busy is de-asserted. If the host does not start data transmission the cycle after MMC Busy is de-asserted, the host shall pull the data lines high (P).
- The host's data transmission shall be an MMC data block containing the data to be written to the registers specified in the MMC command followed by a CRC16.
- Two cycles after the end bit of the data transmission, the device shall transmit the status of the CRC16 for each data line to the host. If the data on all data lines was received successfully and the CRC calculations were correct, a positive CRC shall be indicated by transmitting 010b on DAT0. If the data on any data line was not received successfully or had an incorrect CRC calculation, a negative CRC status shall be indicated by transmitting 101b on DAT0.

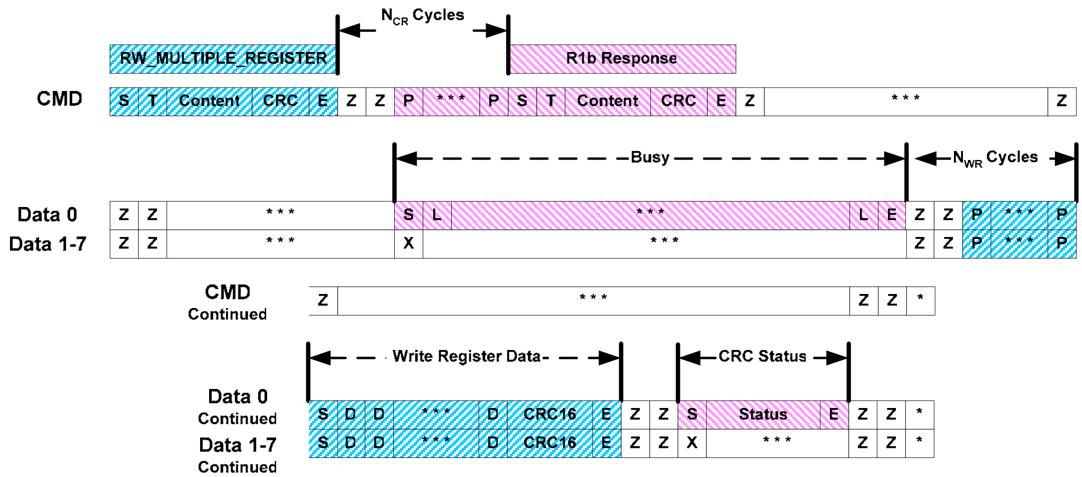


Figure 9 RW_MULTIPLE_REGISTER (CMD60) Write Timings

3.2. RW_MULTIPLE_BLOCK (CMD61) Timing Diagrams

3.2.1. Read Single Block Timings

The host issues a RW_MULTIPLE_BLOCK (CMD61) command to transfer blocks of data from the device. Each MMC data block shall be 512 bytes, 1KB, or 4KB in size with a CRC16 appended to each data line. The amount of data to transfer is specified in the Data Unit Count field of the RW_MULTIPLE_BLOCK (CMD61) command. Before issuing the RW_MULTIPLE_BLOCK (CMD61) command, the host must previously have issued the ATA command to the device using RW_MULTIPLE_REGISTER (CMD60). The following timing requirements shall be met for the RW_MULTIPLE_BLOCK (CMD61) command with WR=0 (R).

- The device shall respond within N_{CR} cycles after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command with an R1 response.
- Within N_{ACIO} cycles after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command, the device shall start transmitting an MMC data block containing the data requested in the ATA command followed by a CRC16 on each data line.
- If interrupts are enabled (nIEN=0 in the ATA Control register), the device shall transmit the start bit of the command completion signal within N_{CCS} cycles after the end bit of the data transmission.

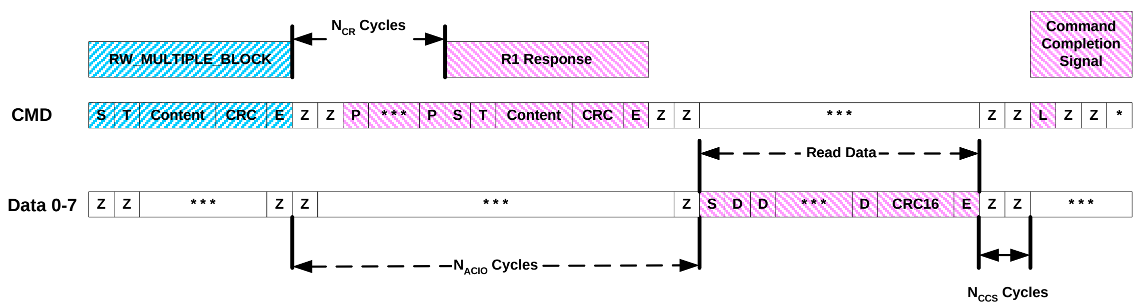


Figure 10 RW_MULTIPLE_BLOCK (CMD61) Single Block Read Timings

3.2.2. Read Multiple Block Timings

If the host issues a RW_MULTIPLE_BLOCK (CMD61) with WR=0 (R) to the device that has a Data Unit Count that is large enough that it requires multiple MMC data blocks to be transferred, then the timings in this section shall be met. This section only describes the requirements for timing between intermediate MMC data block transfers. The timings for the beginning of the MMC command and the end of the MMC command are as described in Section 3.2.1. The requirements to be met include:

- The host and device start the transfer with the same sequences and timings as in the single block read case including the transfer of the first data block for the RW_MULTIPLE_BLOCK (CMD61) command.
- After the device finishes transmitting the first data block it waits N_{ACIO} cycles and starts transmitting the next data block followed by a CRC16 on each data line. N_{ACIO} can vary between each data block.
- Timing and requirements after the last data block is transferred is as described in Section 3.2.1.

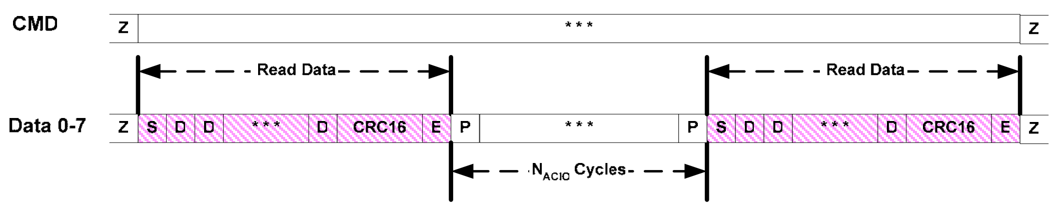


Figure 11 RW_MULTIPLE_BLOCK (CMD61) Multiple Block Read Timings

3.2.3. Write Single Block Timings

The host issues a RW_MULTIPLE_BLOCK (CMD61) command to transfer blocks of data to the device. Each MMC data block shall be 512 bytes, 1KB, or 4KB in size with a CRC16 appended to each data line. The amount of data to transfer is specified in the Data Unit Count field of the RW_MULTIPLE_BLOCK (CMD61) command. Before issuing the RW_MULTIPLE_BLOCK (CMD61) command, the host must previously have issued the ATA command to the device using RW_MULTIPLE_REGISTER (CMD60). The following timing requirements shall be met for a RW_MULTIPLE_BLOCK (CMD61) with WR=1 (W).

- The device shall respond within N_{CR} cycles after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command with an R1b response.
- Two clocks after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command, the device may optionally assert MMC Busy by pulling the DAT0 line low (L) until the device is ready to receive the data block from the host.
- Within N_{WR} cycles after the end bit of the R1b response and MMC Busy is de-asserted, the host shall start transmitting an MMC data block containing the data to be written as part of the ATA command followed by a CRC16 on each data line. The host shall not start data transmission to the device before the end bit of the R1b response is received and MMC Busy is de-asserted. If the host does not start data transmission the cycle after MMC Busy is de-asserted, the host shall pull the data lines high (P).
- The host's data transmission shall be an MMC data block containing the data to be written to the device followed by a CRC16.
- Two cycles after the end bit of the data transmission, the device shall transmit the status of the CRC16 for each data line individually to the host. If the data on all data lines was received successfully and the CRC calculations were correct, a positive CRC shall be indicated by transmitting 010b on DAT0. If the data on any data line was not received successfully or had an incorrect CRC calculation, a negative CRC status shall be indicated by transmitting 101b on DAT0.
- Immediately after the end bit of the CRC status is transmitted, the device may optionally assert MMC Busy.
- If interrupts are enabled (nIEN=0 in the ATA Control register), the device shall transmit the start bit of the command completion signal within N_{CCS} cycles after the end bit of the data transmission and MMC Busy is de-asserted.

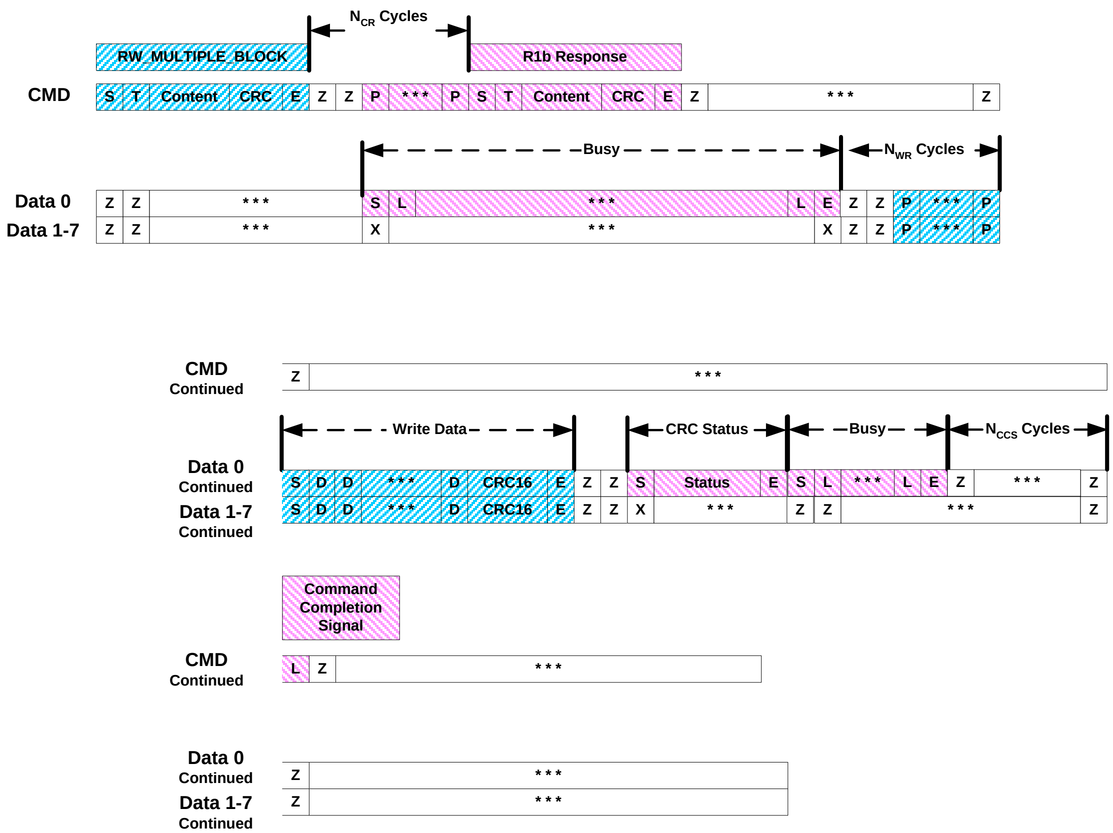
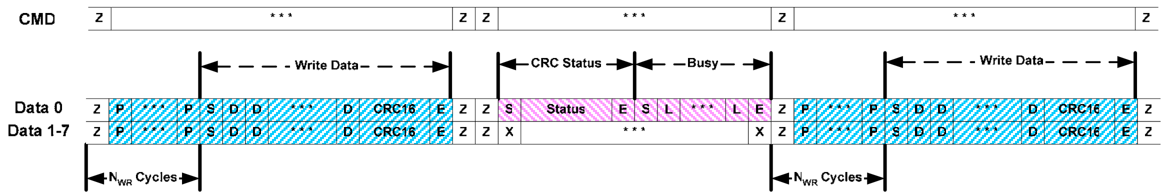


Figure 12 RW_MULTIPLE_BLOCK (CMD61) Single Block Write Timings

3.2.4. Write Multiple Block Timings

If the host issues a RW_MULTIPLE_BLOCK (CMD61) with WR=1 (W) to the device that has a Data Unit Count that is large enough that it requires multiple MMC data blocks to be transferred, then the timings in this section shall be met. This section only describes the requirements for timing between intermediate MMC data block transfers. The timings for the beginning of the MMC command and the end of the MMC command are as described in Section 3.2.3. The requirements to be met include:

- The host and device start the transfer with the same sequences and timings as in the single block write case including the transfer of the first data block for the RW_MULTIPLE_BLOCK (CMD61) command. In Figure 13 the first block of write data corresponds to the data transfer portion of the single block write case.
- Two cycles after the end bit of the data transmission for the first data block, the device shall transmit the status of the CRC16 for each data line individually to the host. If the data on all data lines was received successfully and the CRC calculations were correct, a positive CRC shall be indicated by transmitting 010b on DAT0. If the data on any data line was not received successfully or had an incorrect CRC calculation, a negative CRC status shall be indicated by transmitting 101b on DAT0.
- Immediately after transmission of the CRC status is complete on DAT0, the device may optionally assert MMC Busy by pulling the DAT0 line low (L) until it is ready to receive the next MMC data block from the host.
- Within N_{WR} cycles after the host finishes transmitting the first data block and MMC Busy is de-asserted, the host shall start transmitting the second MMC data block. The host shall not start data transmission to the device before MMC Busy is de-asserted. If the host does not start data transmission the cycle after MMC Busy is de-asserted, the host shall pull the data lines high (P).
- Two cycles after the end bit of the data transmission for the second data block, the device shall transmit the status of the CRC16 for each data line individually to the host. If the data on all data lines was received successfully and the CRC calculations were correct, a positive CRC shall be indicated by transmitting 010b on DAT0. If the data on any data line was not received successfully or had an incorrect CRC calculation, a negative CRC status shall be indicated by transmitting 101b on DAT0.
- Immediately after transmission of the CRC status is complete on DAT0, the device may optionally assert MMC Busy by pulling the DAT0 line low (L) until it is ready to receive the next MMC data block from the host.
- Timing and requirements after the last MMC data block is transferred is as described in Section 3.2.3.



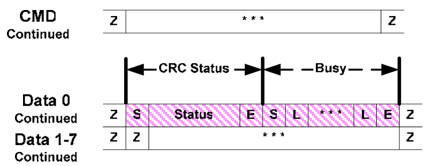


Figure 13 RW_MULTIPLE_BLOCK (CMD61) Multiple Block Write Timings

3.2.5. Non-Data Timings

The host issues a RW_MULTIPLE_BLOCK (CMD61) command with WR=1 (W) and Data Unit Count=0 to enable reception of a command completion signal for a non-data ATA command previously issued with a RW_MULTIPLE_REGISTER (CMD60) command. The following timing requirements shall be met:

- The device shall respond within N_{CR} cycles after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command with an R1b response.
- Two clocks after the end bit of the RW_MULTIPLE_BLOCK (CMD61) command, the device may optionally assert MMC Busy by pulling the DAT0 line low (L).
- If interrupts are enabled (nIEN=0 in the ATA Control register), within N_{CCS} cycles after the end bit of the R1b response, the device shall transmit the command completion signal to the host. The device shall de-assert MMC Busy prior to transmitting the command completion signal.

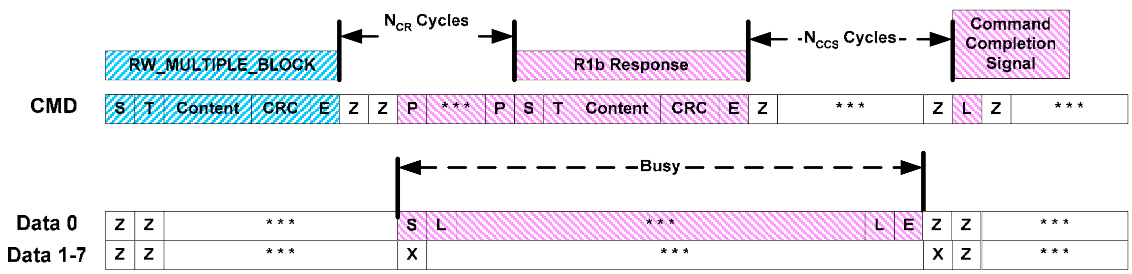


Figure 14 RW_MULTIPLE_BLOCK (CMD61) Non-Data Timings

3.2.6. Command Completion Signal Disable for RW_MULTIPLE_BLOCK (CMD61)

When the host issues a command completion signal disable to the device after the R1(b) response is received for the RW_MULTIPLE_BLOCK (CMD61) command, it is a request for the device to disable its command completion signal. The command completion signal disable does not cause the ATA command to abort and is only used to disable sending a command completion signal for the current ATA command. To abort the ATA command, STOP_TRANSMISSION (CMD12) should be used and its behavior is as defined in the MMC reference.

A command completion signal disable shall only be sent by the host after the R1(b) response for the RW_MULTIPLE_BLOCK (CMD61) is received from the device. The command completion signal disable may be sent while the data lines are active or quiescent; the command completion signal disable does not affect the operation of the data lines.

The command completion signal disable may be preceded by any number of zero bits and may be followed by any number of one bits from the host on the CMD line.

A command completion signal disable is shown in Figure 15. The signal does not impact any data transfer that may be in progress on the data lines; therefore the timing diagram does not include the data lines.

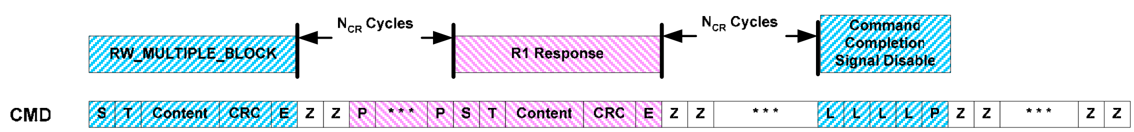


Figure 15 CCS Disable Timings for RW_MULTIPLE_BLOCK (CMD61)

4. Reduced ATA Command Set

The following section defines the Reduced ATA Command Set and its functions and capabilities. The Reduced ATA Command Set provides a streamlined minimal subset of the ATA command set tailored to the core required capabilities necessary to support the needs of handheld and consumer market segments.

4.1. ATA Command Structure

The ATA command structure is defined in Figure 16. The mapping of the ATA command structure to the underlying MMC register space is defined in Figure 6.

Register	7	6	5	4	3	2	1	0
Features	cs							
Features (exp)	cs							
Sector Count	cs							
Sector Count (exp)	cs							
LBA Low	cs							
LBA Low (exp)	cs							
LBA Mid	cs							
LBA Mid (exp)	cs							
LBA High	cs							
LBA High (exp)	cs							
Device/Head	cs							
Command	cs							

Error	cs	cs	cs	cs	cs	ABRT	cs	cs
Status	BSY	DRDY	cs	cs	DRQ	cs	cs	ERR

Figure 16 Generic ATA command structure definition

cs fields have command specific meanings

4.2. Reduced ATA Command Set

Figure 17 lists the Reduced ATA Command Set. Devices that report support for CE-ATA in their initialization signature (see Section 2.4.1) shall support the mandatory Reduced ATA Command Set commands. The behavior for defined CE-ATA commands shall be as specified in this section.

Command	Opcode	Protocol
IDENTIFY DEVICE	ECh	Data-In
READ DMA EXT	25h	Data-In
WRITE DMA EXT	35h	Data-Out
STANDBY IMMEDIATE	E0h	Non-Data
FLUSH CACHE EXT	EAh	Non-Data
Vendor Specific	90h, 92h, 9Ah, C0h-C3h, 80h-8Fh, EFh, F0h, F7h, FAh-FFh	n/a
NOTE: 1. All opcodes not specified in this table may have their behavior defined in a future specification and should be treated as reserved.		

Figure 17 Reduced ATA command set

4.2.1. IDENTIFY DEVICE

The IDENTIFY DEVICE command returns a 512-byte data structure to the host that describes device-specific information and capabilities. The returned data structure is a streamlined version of the ATA IDENTIFY DEVICE data structure where fields that are no longer applicable have been eliminated.

The host shall only issue IDENTIFY DEVICE when the MMC data block size is set to 512 bytes. Issuing IDENTIFY DEVICE with any other MMC data block size setting has indeterminate results. Refer to Section 5.2.8 for MMC data block size settings.

4.2.1.1. Inputs

Register	7	6	5	4	3	2	1	0
Features	Reserved							
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	Reserved							
LBA Low (exp)	Reserved							
LBA Mid	Reserved							
LBA Mid (exp)	Reserved							
LBA High	Reserved							
LBA High (exp)	Reserved							
Device/Head	Reserved							
Command	ECh							

Figure 18 IDENTIFY DEVICE command structure definition

Reserved fields shall be cleared to zero (0).

4.2.1.2. Success Status

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	na							
Sector Count	na							
Sector Count (exp)	na							
LBA Low	na							
LBA Low (exp)	na							
LBA Mid	na							
LBA Mid (exp)	na							
LBA High	na							
LBA High (exp)	na							
Device/Head	na							
Command								
Error	na							
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	0 cs	0 cs	0 ERR

Figure 19 IDENTIFY DEVICE success status definition

na fields have undefined values

4.2.1.3. Error Status

Devices shall not fail the IDENTIFY DEVICE command, although the command may be aborted as a result of the host issuing a STOP_TRANSMISSION (CMD12) command.

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	Reserved							
LBA Low (exp)	Reserved							
LBA Mid	Reserved							
LBA Mid (exp)	Reserved							
LBA High	Reserved							
LBA High (exp)	Reserved							
Device/Head	Reserved							
Command								
Error	R	R	R	R	R	ABRT	R	R
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	0 cs	0 cs	1 ERR

Figure 20 IDENTIFY DEVICE error status definition

ABRT Shall be set to one if the command was aborted by the host.

4.2.1.4. IDENTIFY DEVICE Data Structure Definition

Word	O/M	F/V	Description
0-9			na
10-19	M	F	Serial number (20 ASCII characters)
20-22			na
23-26	M	F	Firmware revision (8 ASCII characters)
27-46	M	F	Model number (40 ASCII characters)
47-59			na
60-61			Obsolete, may be reserved in future
62-79			na
80	M	F	Major version number 15 Set to 1 14-2 Reserved (0) 1 1 = supports CE-ATA version 1.0 0 Set to 0
81-99			na
100-103	M	F	Maximum user LBA
104-105			na
106	M	F	CE-ATA sector size
107			na
108-111	O	F	Device global unique identifier (optional)
112-128			na
129-159	O	X	Vendor specific
160-205			na
206	M	F	CE-ATA Features 15-0 Reserved (0)
207	O	F	Maximum Writes Per Address
208-229			Reserved (0)
230-254			na
255	M	X	Integrity word 15-8 Checksum (as defined in ATA) 7-0 Signature (as defined in ATA)
Key: O/M = Mandatory/optional requirement. M = Support of the word is mandatory. O = Support of the word is optional. F/V = Fixed/variable content F = the content of the word is fixed and does not change. For removable media devices, these values may change when media is removed or changed. V = the contents of the word is variable and may change depending on the state of the device or the commands executed by the device. X = the content of the word may be fixed or variable. na = Optional fields. If implemented shall be as defined in the ATA reference.			

Figure 21 IDENTIFY DEVICE data structure field definitions

4.2.1.5. Words 10-19: Serial Number

Words 10-19 shall be as defined in the ATA reference.

4.2.1.6. Words 23-26: Firmware Revision

Words 23-26 shall be as defined in the ATA reference.

4.2.1.7. Words 27-46: Model Number
Words 27-46 shall be as defined in the ATA reference.

4.2.1.8. Word 80: Major Version Number
Word 80 indicates the CE-ATA specification major revision number that the device complies with.

4.2.1.9. Words 100-103: Maximum User LBA
Words 100-103 define the addressable capacity of the device. The value in words 100-103 shall be the total user storage capacity of the device in bytes divided by 512.

4.2.1.10. Word 106: CE-ATA sector size
Word 106 indicates the CE-ATA sector size. All device media accesses shall be in full units of the device's reported CE-ATA sector size and shall be aligned on boundaries an integral multiple of the reported CE-ATA sector size. IDENTIFY DEVICE has a fixed data size of 512 bytes. The value in word 106 is reported in terms of a power of 2. For instance, a reported value of 14 corresponds to a CE-ATA sector size of 2^{14} or 16384 bytes. A value smaller than 12 (i.e. 4096 bytes) is not supported.

4.2.1.11. Words 108-111: Device Global Unique Identifier
If word 108-111 are not 0 or 0FFFFFFFFh, the field contains the IEEE global unique identified (GUID) for the device.

4.2.1.12. Word 206: CE-ATA Features
Word 206 indicates optional CE-ATA features that are supported by the device.

No optional features are currently defined. All bits in this word are reserved.

4.2.1.13. Word 207: Maximum Writes Per Address
Word 207 indicates the number of write accesses supported per addressable sector. If the field has the value 0FFFFh, the device reports an unrestricted number of writes per addressable sector. The maximum writes per address value in word 207 is reported in terms of a power of 2 according to the formula $MaxWrites=2^{Word207}-1$. For instance, a reported value of 20 corresponds to $2^{20} - 1$ writes or roughly 1 million write cycles, while a value of 1 corresponds to $2^{1} - 1$ writes or a write-once media. A read-only device shall report a value of 0.

4.2.2. READ DMA EXT
The Reduced ATA Command Set does not have a number of different data transfer modes, so only a single high-level block read command is defined. The READ DMA EXT command reads a number of logical blocks of data from the device using the Data-In data transfer protocol. The name used for this operation is historical and inherited from the ATA specification.

4.2.2.1. Inputs

Register	7	6	5	4	3	2	1	0
Features	Reserved							
Features (exp)	Reserved							
Sector Count	Sector Count (7:3)					0	0	0
Sector Count (exp)	Sector Count (15:8)							
LBA Low	LBA (7:3)					0	0	0
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	Reserved							
Command	25h							

Figure 22 READ DMA EXT command structure definition

Sector Count (15:0) — Number of 512 byte units of data to be transferred. Hosts shall not specify a value of zero for this field; the device behavior when this value is zero is indeterminate. The Sector Count shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE. For example, if the Word 106 value is 8KB then Sector Count (3:0) shall be zero.

LBA (47:0) — Starting logical block number for the transfer. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE. For example, if the Word 106 value is 8KB then LBA (3:0) shall be zero.

Reserved — Reserved fields shall be cleared to zero (0).

4.2.2.2. Success Status

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	na							
Sector Count	na							
Sector Count (exp)	na							
LBA Low	LBA (7:0)							
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	na							
Command								

Error	na							
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	SPT cs	OVR cs	0 ERR

Figure 23 READ DMA EXT success status definition

OVR — Shall be set to one if the command encountered an internal device buffer overflow condition due to the host failing to accept data from the device at a sufficiently high rate. This condition is not an error condition although performance is impacted. Hosts with poor interface performance may cause devices to slip revolutions.

SPT — If set to one, indicates that at least one block in the LBA region read is considered suspect by the device. The device was able to return correct data, but recommends that the host remap suspect blocks at the next opportunity. If cleared to zero, the device does not consider any of the data blocks suspect.

LBA — If SPT is set to one, then the LBA field indicates the first LBA of the first suspect block. There may be more than one suspect block in the region. It is the host's responsibility to perform additional operations to determine exactly which blocks are suspect. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE.

na fields have undefined values

4.2.2.3. Error Status

An unrecoverable error encountered during the execution of this command causes the data transfer to cease at a transfer boundary determined by the device. Except in the case where the host aborts the transfer, the device is required to cease data transfer at an MMC block boundary. Some of the data transferred when an error condition is reported may be incorrect and the host must determine from the status indication the point in the transfer where the error is encountered (and the point at which returned data may be incorrect).

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	LBA (7:0)							
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	Reserved							
Command								

Error	ICRC	UNC	R	IDNF	R	ABRT	R	R
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	0 cs	OVR cs	1 ERR

Figure 24 READ DMA EXT error status definition

LBA (47:0) The logical block address of the first unrecoverable error encountered. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE.

ICRC Shall be set to one if an interface communication error occurred during the data transfer.

UNC Shall be set to one if the data from the device media is uncorrectable.

IDNF Shall be set to one if the indicated sector is not user addressable. This is typically as a result of the sector address being past the end of the drive or the specified LBA not adhering to the constraints defined by Word 106 of IDENTIFY DEVICE.

ABRT Shall be set to one if the host aborted the command by issuing the STOP_TRANSMISSION (CMD12) command or if there was an underlying protocol error.

OVR Shall be set to one if the command encountered an internal device buffer overflow condition due to the host failing to accept data from the device at a sufficiently high rate. This condition is not an error condition although performance is impacted. Hosts with poor interface performance may cause devices to slip revolutions.

Reserved/R Reserved fields shall be cleared to zero (0).

4.2.3. WRITE DMA EXT

The Reduced ATA Command Set does not have a number of different data transfer modes, so only a single high-level block write command is defined. The WRITE DMA EXT command writes a number of logical blocks of data to the device using the Data-Out data transfer protocol. The name used for this operation is historical and inherited from the ATA specification and there is no DMA transfer distinction.

Note that completion of the WRITE DMA EXT command does not necessarily mean that the written data has been committed to the device media. See the FLUSH CACHE EXT command for information on committing written data to media.

4.2.3.1. Inputs

Register	7	6	5	4	3	2	1	0
Features	Reserved							
Features (exp)	Reserved							
Sector Count	Sector Count (7:3)					0	0	0
Sector Count (exp)	Sector Count (15:8)							
LBA Low	LBA (7:3)					0	0	0
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	Reserved							
Command	35h							

Figure 25 WRITE DMA EXT command structure definition

Sector Count (15:0) — Number of 512 byte units of data to be transferred. Hosts shall not specify a value of zero for this field; the device behavior when this value is zero is indeterminate. The Sector Count shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE. For example, if the Word 106 value is 8KB then Sector Count (3:0) shall be zero.

LBA (47:0) — Starting logical block number for the transfer. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE. For example, if the Word 106 value is 8KB then LBA (3:0) shall be zero.

Reserved — Reserved fields shall be cleared to zero (0).

4.2.3.2. Success Status

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	na							
Sector Count	na							
Sector Count (exp)	na							
LBA Low	LBA (7:0)							
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	na							
Command								

Error	na							
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	SPT cs	UFL cs	0 ERR

Figure 26 WRITE DMA EXT success status definition

UFL — Shall be set to one if the command encountered an internal device buffer underflow condition due to the host failing to deliver data to the device at a sufficiently high rate. This condition is not an error condition although performance is impacted. Hosts with poor interface performance may cause devices to slip revolutions.

SPT — If set to one, indicates that at least one block in the LBA region written is considered suspect by the device. The device was able to write correct data, but recommends that the host remap suspect blocks at the next opportunity. If cleared to zero, the device does not consider any of the data blocks suspect.

LBA — If SPT is set to one, then the LBA field indicates the first LBA of the first suspect block. There may be more than one suspect block in the region. It is the host's responsibility to perform additional operations to determine exactly which blocks are suspect. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE.

na fields have undefined values

4.2.3.3. Error Status

An unrecoverable error encountered during the execution of this command causes the data transfer to cease at a transfer boundary determined by the device. Some of the data transferred when an error condition is reported may not be written to the device and the host must determine from the status indication the point in the transfer where the error is encountered (and the point at which transferred data may not have been written to the device).

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	LBA (7:0)							
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	Reserved							
Command								

Error	ICRC	UNC	R	IDNF	R	ABRT	R	R
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	0 cs	UFL cs	1 ERR

Figure 27 WRITE DMA EXT error status definition

LBA (47:0) — The logical block address of the first unrecoverable error encountered. The LBA shall be specified in 512 byte size units and shall be constrained based on the value in Word 106 of IDENTIFY DEVICE.

ICRC — Shall be set to one if an interface communication error occurred during the data transfer.

UNC — Shall be set to one if the operating conditions of the device were such that the data could not be reliably written to the media.

IDNF — Shall be set to one if the indicated sector is not user addressable. This is typically as a result of the sector address being past the end of the drive or the specified LBA not adhering to the constraints defined by Word 106 of IDENTIFY DEVICE.

ABRT — Shall be set to one if the host aborted the command by terminating the transfer using STOP_TRANSMISSION (CMD12) or there is an underlying protocol error.

UFL — Shall be set to one if the command encountered an internal device buffer underflow condition due to the host failing to deliver data to the device at a sufficiently high rate. This condition is not an error condition although performance is impacted. Hosts with poor interface performance may cause devices to slip revolutions.

Reserved — Reserved fields shall be cleared to zero (0).

4.2.4. STANDBY IMMEDIATE

The STANDBY IMMEDIATE command causes the device to immediately enter its most aggressive power management mode that still retains internal device context. The device shall be capable of receiving a new command after executing this command. For devices with rotating media, the device shall not spin-up until a host command is received that requires media access. The device shall ensure data coherency prior to returning successful status for this command.

For devices with rotating media, the host cannot rely on the device to retract the head immediately upon reception of this command.

For devices that do not provide a power savings mode, the STANDBY IMMEDIATE command shall return a successful status indication.

The host shall complete a STANDBY IMMEDIATE command or a FLUSH CACHE EXT command prior to powering off the device.

4.2.4.1. Inputs

Register	7	6	5	4	3	2	1	0
Features	Reserved							
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	Reserved							
LBA Low (exp)	Reserved							
LBA Mid	Reserved							
LBA Mid (exp)	Reserved							
LBA High	Reserved							
LBA High (exp)	Reserved							
Device/Head	Reserved							
Command	E0h							

Figure 28 STANDBY IMMEDIATE command structure definition

Reserved fields shall be cleared to zero (0).

4.2.4.2. Success Status

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	na							
Sector Count	na							
Sector Count (exp)	na							
LBA Low	na							
LBA Low (exp)	na							
LBA Mid	na							
LBA Mid (exp)	na							
LBA High	na							
LBA High (exp)	na							
Device/Head	na							
Command								

Error	na							
Status	0 BSY	1 DRDY	0 cs	0 cs	0 DRQ	0 cs	0 cs	0 ERR

Figure 29 STANDBY IMMEDIATE success status definition

na fields have undefined values

4.2.4.3. Error Status

Devices shall not fail the STANDBY IMMEDIATE command and there is no error status condition defined for the command.

4.2.5. FLUSH CACHE EXT

For devices that buffer/cache written data, the FLUSH CACHE EXT command ensures buffered data is written to the device media. Upon the successful execution of the FLUSH CACHE EXT command, the device shall have no volatile user data and shall be in a state that permits power to be removed without any user data loss. All buffered data must be committed to nonvolatile media prior to signaling completion of this command.

For devices that do not buffer written data, the FLUSH CACHE EXT command shall return a successful status indication.

The host shall complete a FLUSH CACHE EXT command or a STANDBY IMMEDIATE command prior to powering off the device.

4.2.5.1. Inputs

Register	7	6	5	4	3	2	1	0
Features	Reserved							
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	Reserved							
LBA Low (exp)	Reserved							
LBA Mid	Reserved							
LBA Mid (exp)	Reserved							
LBA High	Reserved							
LBA High (exp)	Reserved							
Device/Head	Reserved							
Command	EAh							

Figure 30 FLUSH CACHE EXT command structure definition

Reserved fields shall be cleared to zero (0).

4.2.5.2. Success Status

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	na							
Sector Count	na							
Sector Count (exp)	na							
LBA Low	na							
LBA Low (exp)	na							
LBA Mid	na							
LBA Mid (exp)	na							
LBA High	na							
LBA High (exp)	na							
Device/Head	na							
Command								

Error	na							
Status	0 BSY	1 DRDY	0 DF	0 cs	0 DRQ	0 cs	0 cs	0 ERR

Figure 31 FLUSH CACHE EXT success status definition

na fields have undefined values

4.2.5.3. Error Status

An unrecoverable error encountered during the execution of this command causes the command to cease committing further buffered data to nonvolatile storage and reports the LBA number of the block that failed to commit. Further FLUSH CACHE EXT commands shall continue to commit buffered write data to nonvolatile storage starting with the first sector after the failed one.

Register	7	6	5	4	3	2	1	0
Features								
Features (exp)	Reserved							
Sector Count	Reserved							
Sector Count (exp)	Reserved							
LBA Low	LBA (7:0)							
LBA Low (exp)	LBA (31:24)							
LBA Mid	LBA (15:8)							
LBA Mid (exp)	LBA (39:32)							
LBA High	LBA (23:16)							
LBA High (exp)	LBA (47:40)							
Device/Head	Reserved							
Command								

Error	R	R	R	R	R	ABRT	R	R
Status	0 BSY	1 DRDY	DF	0 cs	0 DRQ	0 cs	0 cs	1 ERR

Figure 32 FLUSH CACHE EXT error status definition

LBA (47:0) The logical block address of the first unrecoverable error encountered. The LBA shall be specified in 512-byte size units and

	shall be constrained based on the value in Word 106 of IDENTIFY DEVICE.
DF	DF (Device Fault) shall be set to one if a device fault has occurred.
ABRT	Set to one.
Reserved	Reserved fields shall be cleared to zero (0).

5. Status and Control Registers

The following section defines the Status and Control Registers (SCRs) and their functions. The protocol for accessing the Status and Control Registers is defined in Section 2. Figure 33 shows how the MMC register space is allocated.

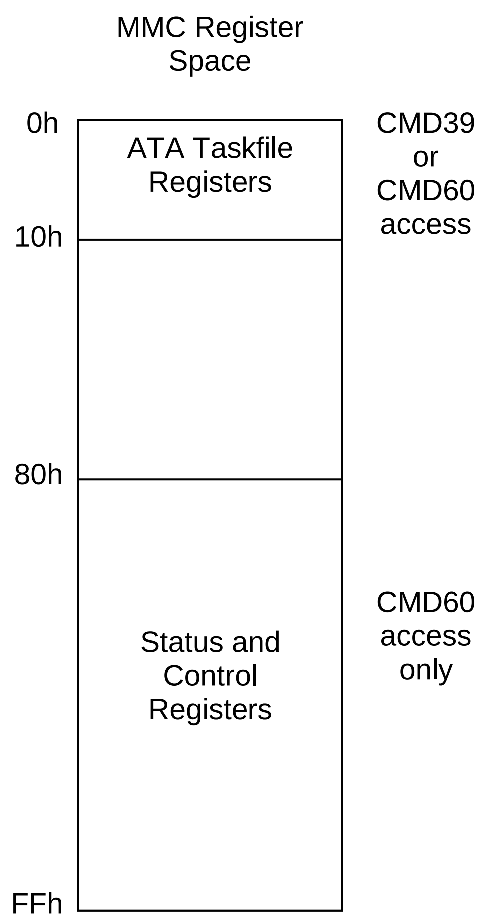


Figure 33 MMC Register Space

5.1. Access Primitives

There are only two operations that can be performed on the Status and Control Registers – reading a register and writing a register. The functions performed by the registers in response to being read/written are defined in the following sections. The Status and Control Registers are accessed using the RW_MULTIPLE_REGISTER (CMD60) command.

5.1.1. Register Read

Reading undefined register address returns an indeterminate value. The Register Read operation has no error conditions. The protocol definition for the Register Read function is defined in Section 2.

5.1.2. Register Write

Writing undefined or unsupported registers shall have no effect. The Register Write operation has no error conditions. The protocol definition for the Register Write function is defined in Section 2.

5.2. Register Definition

All registers are 32 bits in size and no partial access to the registers is accommodated. A read of a Status and Control register shall provide a self-consistent image of that register. Registers that only define a few bits shall return zeroes for the unused/undefined bits. The Status and Control registers start at MMC register address 80h. All register access shall be Dword aligned and for one or more Dwords in length.

Bit 31 of each register indicates whether that register is supported. Bit 30 of each register indicates whether the value in bits 29-0 in a supported register is valid. For values that are persistent across power cycles, the valid bit in the register may not be asserted until device spin-up has occurred if the persistent values are stored on the media.

Figure 34 lists the defined registers. The functions provided by the internal registers are intended to expose information on the operating conditions of the device to permit hosts to provide services similar to those provided by SMART. Hosts may also utilize the internal register data to control the operation of the device. For example, hosts may elect to not attempt to spin-up a device if the environmental conditions are not favorable due to extreme heat or cold.

Register Index	Byte Address	Register Name	M/O	R/W	Description
0	80h	scrTempC	O	RO	Current temperature reading
1	84h	scrTempMaxP	O	RO	Peak maximum temperature reading
2	88h	scrTempMinP	O	RO	Peak minimum temperature reading
3	8Ch	scrStatus	O	RO	Status information for the device
4	90h	scrReallocsA	O	RO	Accumulated number of reallocated ATA sectors
5	94h	scrERetractsA	O	RO	Accumulated number of uncontrolled retracts
6	98h	scrCapabilities	M	RO	Capabilities and features of device
7-15	9Ch – BFh	Reserved	na	RO	Reserved for future definition
16	A0h	scrControl	M	RW	Control capabilities of device
17-23	A4h – DFh	Reserved	na	RW	Reserved for future definition
24-31	E0h – FFh	Vendor Specific	na	RW	Vendor specific registers
Key: M/O = Mandatory/optional requirement. M = Support of the register is mandatory. O = Support of the register is optional. R/W = Read/write support. RO = The register is read-only. RW = The register may be read or written.					

Figure 34 Status and Control Register Map

5.2.1. scrTempC Register

The scrTempC register holds the current temperature value of the device. The rate at which the device updates the temperature value is vendor specific. The resolution of the temperature value is vendor specific.

Bits 15-0 is a two's complement value of the number of degrees Celsius.

Bits 29-16 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.2. scrTempMaxP Register

The scrTempMaxP register holds the latched peak maximum temperature value of the device. Reading the register returns the highest temperature value the device has registered. The device shall update the register with a new value if the present temperature indication is greater than the value held in the register. The rate at which the device updates the maximum latched temperature value is vendor specific and the means by which the device determines the maximum temperature encountered is vendor specific. The resolution of the maximum temperature value is vendor specific.

Bits 15-0 is a two's complement value of the number of degrees Celsius. This value shall be persistent across power cycles.

Bits 29-16 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.3. scrTempMinP Register

The scrTempMinP register holds the latched peak minimum temperature value of the device. Reading the register returns the lowest temperature value the device has registered. The device shall update the register with a new value if the present temperature indication is lower than the value held in the register. The rate at which the device updates the minimum latched temperature value is vendor specific and the means by which the device determines the minimum temperature encountered is vendor specific. The resolution of the minimum temperature value is vendor specific.

Bits 15-0 is a two's complement value of the number of degrees Celsius. This value shall be persistent across power cycles.

Bits 29-16 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.4. scrStatus Register

The scrStatus register specifies status information for the operation of the device.

Bit 0 is read-only. Bit 0 when set to one indicates that the device has experienced excessive abuse due to shock or other handling. Bit 0 when cleared to zero indicates that the device has not experienced excessive abuse as measured by the device. The method for determining when to set this bit is vendor specific. This value shall be persistent across power cycles.

Bits 29-1 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.5. scrReAllocsA Register

The scrReAllocsA register holds the accumulated number of CE-ATA sector reallocations performed, including reallocations that occur due to read or write operations. A reallocation is when a portion of a CE-ATA sector is moved from a bad location to a spare location. The ReAllocsA register provides an indication to host software of the number of grown defects that have been discovered over the life of the device.

Bits 29-0 holds the accumulated number of CE-ATA sector reallocations performed over the life of the device. This value shall be persistent across power cycles.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.6. scrERetractsA Register

The scrERetractsA register holds the accumulated number of uncontrolled retracts over the life of the device. A retract is an unloading of the head from the disk. This register is only supported by devices that have rotating media. Support for this register is optional, but devices that do support it shall ensure the value is persistent across all event types including power cycles.

Bits 29-0 holds the accumulated number of uncontrolled retracts performed over the life of the device. This value shall be persistent across power cycles.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.7. scrCapabilities

The scrCapabilities register specifies the capabilities and features of the device.

Bit 0 is read-only and shall be set to one. Bit 0 indicates that the device supports an MMC data block size of 512 bytes.

Bit 1 is read-only. Bit 1 if set to one indicates that the device supports an MMC data block size of 1KB. Bit 1 if cleared to zero indicates that the device does not support an MMC data block size of 1KB.

Bit 2 is read-only. Bit 2 if set to one indicates that the device supports an MMC data block size of 4KB. Bit 2 if cleared to zero indicates that the device does not support an MMC data block size of 4KB.

Bits 29-3 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

This register is not affected by reception of the MMC command GO_IDLE_STATE (CMD0) or by an ATA software reset.

5.2.8. scrControl

The scrControl register is used to control the operation of the device.

Bits 1-0 control the MMC data block size. The MMC data block size is encoded as follows:

- 00b – MMC data block size is 512 bytes
- 01b – MMC data block size is 1KB
- 10b – MMC data block size is 4KB
- 11b – Reserved

By default, this field is 00b corresponding to an MMC data block size of 512 bytes. The host shall only set the MMC data block size to a value that the device supports as specified in the scrCapabilities register.

Bits 29-2 are reserved.

Bit 30 if set to one indicates that the values in bits 29-0 are valid. Bit 30 if cleared to zero indicates that the values in bits 29-0 are not valid and should not be used.

Bit 31 if set to one indicates that the register is supported by the device. Bit 31 if cleared to zero indicates that the register is not supported by the device. When bit 31 is cleared to zero, bits 30-0 have indeterminate values.

When MMC command GO_IDLE_STATE (CMD0) is received, this register shall be reset to its default values. This register is not affected by reception of an ATA software reset.

APPENDIX A. CE-ATA COMMAND EXAMPLE

A.1 Overview

This informative appendix is designed to illustrate the process by which the host issues CE-ATA commands. The examples shown are for informative purposes only and are not meant to imply exact host or device behavior.

A.1.1 ATA Task File Definitions

Figure 35 shows the field definitions of the ATA task file as used by a READ DMA EXT or WRITE DMA EXT. The ATA task file is mapped in MMC register space starting at address 0h.

Address	Register	7	6	5	4	3	2	1	0
0h	Reserved	Reserved							
1h	Features (exp)	Reserved							
2h	Sector Count (exp)	Sector Count (15:8)							
3h	LBA Low (exp)	LBA (31:24)							
4h	LBA Mid (exp)	LBA (39:32)							
5h	LBA High (exp)	LBA (47:40)							
6h	Control	Reserved					SRST	nIEN	0
7h	Reserved	Reserved							
8h	Reserved	Reserved							
9h	Features (Write Only)	Reserved							
9h	Error (Read Only)	ICRC	UNC	MC	IDNF	MCR	ABRT	NM	R
Ah	Sector Count	Sector Count (7:3)					0	0	0
Bh	LBA Low	LBA (7:3)					0	0	0
Ch	LBA Mid	LBA (15:8)							
Dh	LBA High	LBA (23:16)							
Eh	Device/Head	0	1	0	0	Reserved			
Fh	Command (Write Only)	Command							
Fh	Status (Read Only)	BSY	DRDY	DF	R	DRQ	R	R	ERR

Figure 35 ATA Task File Field Definitions for READ/WRITE DMA EXT

A.1.2 MMC Block Timing Diagrams

The block timing diagrams in this appendix are drawn at the MMC bus token level of detail to clearly illustrate the examples and avoid low-level detail. Timing diagram abbreviations, identifiers, and exact timing requirements are detailed in Section 3 and in the MMC reference.

A.2 READ DMA EXT Example

This section will provide an overview of an ATA read command that requests an 8KB data transfer starting at LBA 100h with interrupts enabled. In this example, both the host and device are in the MMC TRAN state and have completed initialization.

A.2.1 ATA Task File

Figure 36 shows how the host programs the ATA task file registers for a READ DMA EXT command with an LBA of 100h and a data transfer size of 8KB. The Sector Count is set to 10h, corresponding to 16 512 byte units of data to transfer. The nIEN bit in the Control register is cleared to 0 to enable interrupts for this ATA command.

Address	**Register**	**7**	**6**	**5**	**4**	**3**	**2**	**1**	**0**
0h	Reserved	0							
1h	Features (exp)	0							
2h	Sector Count (exp)	0							
3h	LBA Low (exp)	0							
4h	LBA Mid (exp)	0							
5h	LBA High (exp)	0							
6h	Control	0					0	0	0
7h	Reserved	0							
8h	Reserved	0							
9h	Features	0							
Ah	Sector Count	10h							
Bh	LBA Low	0							
Ch	LBA Mid	1h							
Dh	LBA High	0							
Eh	Device/Head	0	1	0	0	0			
Fh	Command	25h							

Figure 36 Task File Register Parameters for READ DMA EXT Example

A.2.2 READ DMA EXT Command Sequence

To issue the READ DMA EXT command, the host will transmit a RW_MULTIPLE_REGISTER (CMD60) command that writes the 16 bytes of the ATA task file as shown in Figure 37 to the device. The data transfer of the register contents occurs after the host receives the MMC response for the RW_MULTIPLE_REGISTER (CMD60) command.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_REGISTER (60)					
			1	1	1	1	0	0
4	WR 1	Reserved (0)						
3	Address [7:0] (value =0h)							
2	Reserved (0)							
1	Byte Count [7:0] (value =10h)							
0	CRC							1

Figure 37 RW_MULTIPLE_REGISTER (CMD60) Parameters for READ DMA EXT Example

After issuing the ATA command to the device with the RW_MULTIPLE_REGISTER (CMD60) command, the host will transmit a RW_MULTIPLE_BLOCK (CMD61) command to initiate transfer of block data from the device to the host. Since the ATA request is a read operation the WR bit will be cleared to zero to indicate that data is going to be transferred from the device to the host. Interrupts are enabled for this ATA command so the data transfer must be completed using one RW_MULTIPLE_BLOCK (CMD61) command. Therefore the Data Unit Count will be set to 10h to indicate that the entire transfer of 8KB of data will be transferred as part of the RW_MULTIPLE_BLOCK (CMD61) command.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_BLOCK (61)					
			1	1	1	1	0	1
4	WR 0	Reserved (0)						
3	Reserved (0)							
2	Data Unit Count [15:8] (value = 00h)							
1	Data Unit Count [7:0] (value = 10h)							
0	CRC							1

Figure 38 RW_MULTIPLE_BLOCK (CMD61) Parameters for READ DMA EXT Example

After the host transmits the RW_MULTIPLE_BLOCK (CMD61) command the device will issue an MMC response to the host indicating the RW_MULTIPLE_BLOCK (CMD61) command was received. The device will begin transferring MMC data blocks to the host to satisfy the transfer size indicated in the RW_MULTIPLE_BLOCK (CMD61) command. If the MMC data block transfer size is 512 bytes, the device will send 16 MMC data blocks to the host to complete the 8KB data transfer. If the MMC data bock size is 1KB, the device will send eight MMC data blocks to the host to complete the transfer. If the MMC data block transfer size is 4KB, the device will send two MMC data blocks to the host to complete the transfer.

After the data transfer is complete and the ATA command is finished, the device will signal an interrupt to the host by sending a command completion signal. After detecting the command completion signal, the host will issue a FAST_IO (CMD39) command to read the ATA Status register at Register Address 15 to determine the ending status of the ATA command.

The device will send an MMC R4 response to complete the FAST_IO (CMD39) command. The R4 response will contain the ATA Status register value. If the ATA command completed in error, as indicated by the ERR bit being set to one in the ATA Status register value, the host may issue additional FAST_IO (CMD39) commands to read the ATA Error register and other ATA registers to determine why the ATA command failed.

A.2.3 MMC Bus Transactions

Figure 39 show a possible series of high level MMC transactions that are performed to execute the READ DMA EXT command. In this example the data will be transferred in two 4KB MMC data blocks.

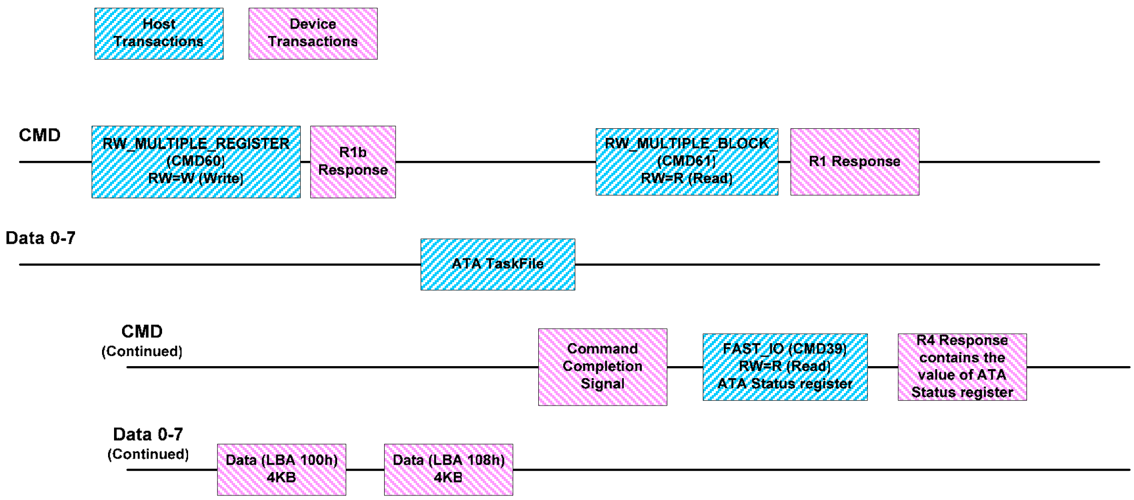


Figure 39 Block Timing Diagram for READ DMA EXT example

A.3 WRITE DMA EXT Example

This section will provide an overview of an ATA write command that writes 4KB (one 4KB sector) of data to the device starting at LBA 100h with interrupts enabled. In this example, both the host and device are in the MMC TRAN state and have completed initialization.

A.3.1 ATA Task File

Figure 40 shows how the host programs the ATA task file registers for a WRITE DMA EXT command with an LBA of 100h and a data transfer of 4KB. The Sector Count is set to 8h, corresponding to eight 512 byte units of data to transfer. The nIEN bit in the Control register is cleared to zero to enable interrupts for this ATA command.

<table>
<tr><th>Address</th><th>Register</th><th>7</th><th>6</th><th>5</th><th>4</th><th>3</th><th>2</th><th>1</th><th>0</th></tr>
<tr><td>0h</td><td>Reserved</td><td colspan="8">0</td></tr>
<tr><td>1h</td><td>Features (exp)</td><td colspan="8">0</td></tr>
<tr><td>2h</td><td>Sector Count (exp)</td><td colspan="8">0</td></tr>
<tr><td>3h</td><td>LBA Low (exp)</td><td colspan="8">0</td></tr>
<tr><td>4h</td><td>LBA Mid (exp)</td><td colspan="8">0</td></tr>
<tr><td>5h</td><td>LBA High (exp)</td><td colspan="8">0</td></tr>
<tr><td>6h</td><td>Control</td><td colspan="5">0</td><td>0</td><td>0</td><td>0</td></tr>
<tr><td>7h</td><td>Reserved</td><td colspan="8">0</td></tr>
<tr><td>8h</td><td>Reserved</td><td colspan="8">0</td></tr>
<tr><td>9h</td><td>Features</td><td colspan="8">0</td></tr>
<tr><td>Ah</td><td>Sector Count</td><td colspan="8">8h</td></tr>
<tr><td>Bh</td><td>LBA Low</td><td colspan="8">0</td></tr>
<tr><td>Ch</td><td>LBA Mid</td><td colspan="8">1h</td></tr>
<tr><td>Dh</td><td>LBA High</td><td colspan="8">0</td></tr>
<tr><td>Eh</td><td>Device/Head</td><td>0</td><td>1</td><td>0</td><td>0</td><td colspan="4">0</td></tr>
<tr><td>Fh</td><td>Command</td><td colspan="8">35h</td></tr>
</table>

Figure 40 Task File Register Parameters for WRITE DMA EXT Example

A.3.2 WRITE DMA EXT Command Sequence

To issue the WRITE DMA EXT command, the host will transmit a RW_MULTIPLE_REGISTER (CMD60) command that writes the 16 bytes of the ATA task file as shown in Figure 40 to the device. The data transfer of the register contents occurs after the host receives the MMC response for the RW_MULTIPLE_REGISTER (CMD60) command.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_REGISTER (60) 1	1	1	1	0	0
4	WR 1	Reserved (0)						
3	Address [7:0] (value =0h)							
2	Reserved (0)							
1	Byte Count [7:0] (value =10h)							
0	CRC							1

Figure 41 RW_MULTIPLE_REGISTER (CMD60) Parameters for WRITE DMA EXT Example

After issuing the ATA command to the device with the RW_MULTIPLE_REGISTER (CMD60) command, the host will transmit a RW_MULTIPLE_BLOCK (CMD61) command to initiate transfer of block data from the device to the host. Since the ATA request is a write operation the WR bit will be set to 1 to indicate that data is going to be transferred from the host to the device. Interrupts are enabled for this command so the data transfer must be completed using one RW_MULTIPLE_BLOCK (CMD61) command. Therefore the Data Unit Count will be set to 8h to indicate that the entire transfer of 4KB of data will be transferred as part of the RW_MULTIPLE_BLOCK (CMD61) command. If the device is not ready to accept data immediately from the host, the device may assert MMC Busy to delay the start of the data transfer from the host to the device.

	7	6	5	4	3	2	1	0
5	0	1	RW_MULTIPLE_BLOCK (61) 1	1	1	1	0	1
4	WR 1	Reserved (0)						
3	Reserved (0)							
2	Data Unit Count [15:8] (value = 0h)							
1	Data Unit Count [7:0] (value = 8h)							
0	CRC							1

Figure 42 RW_MULTIPLE_BLOCK (CMD61) Parameters for WRITE DMA EXT Example

After the host transmits the RW_MULTIPLE_BLOCK (CMD61) command the device will issue an MMC response to the host indicating the RW_MULTIPLE_BLOCK (CMD61) command was received. The host will begin transferring MMC data blocks to the device to satisfy the transfer size indicated in the RW_MULTIPLE_BLOCK (CMD61) command after MMC Busy is de-asserted. If the MMC data block transfer size is 512 bytes, the host will send eight MMC data blocks to the device to complete the 8KB data transfer. If the MMC data block transfer size is 1KB, the host will send four MMC data blocks to the device to complete the transfer. If the MMC data block transfer size is 4KB, the host will send one MMC data blocks to the device to complete the transfer.

After the data transfer is complete and the command is finished, the device will signal an interrupt to the host by sending a command completion signal. After detecting the command completion signal, the host will issue a FAST_IO (CMD39) command to read the ATA Status register at Register Address 15 to determine the ending status of the ATA command.

The device will send an MMC R4 response to complete the FAST_IO (CMD39) command. The R4 response will contain the ATA Status register value. If the command completed in error, as indicated by the ERR bit being set to one in the ATA Status register value, the host may issue additional FAST_IO (CMD39) commands to read the ATA Error register and other ATA registers to determine why the command failed.

A.3.3 MMC Bus Transactions

Figure 43 show a possible series of high level MMC transactions that are performed to execute the WRITE DMA EXT command. In this example the data will be transferred in four 1KB MMC data blocks.

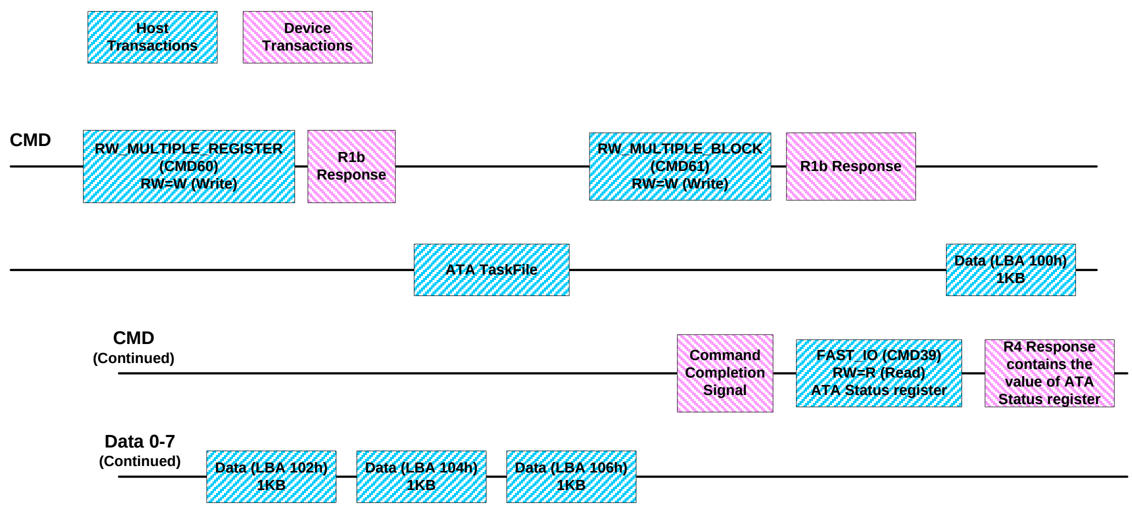


Figure 43 Block Timing Diagram for WRITE DMA EXT Example